# REBECCA MARK IIB (AUST.)

ISSUED FOR THE INFORMATION AND GUIDANCE OF ALL CONCERNED

By Command of the Air Board,

Secretary.

R.A.A.F. PUBLICATION No. 820

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The AMENDMENTS promulgated in the undermentioned Amendment Lists have been made in this publication.

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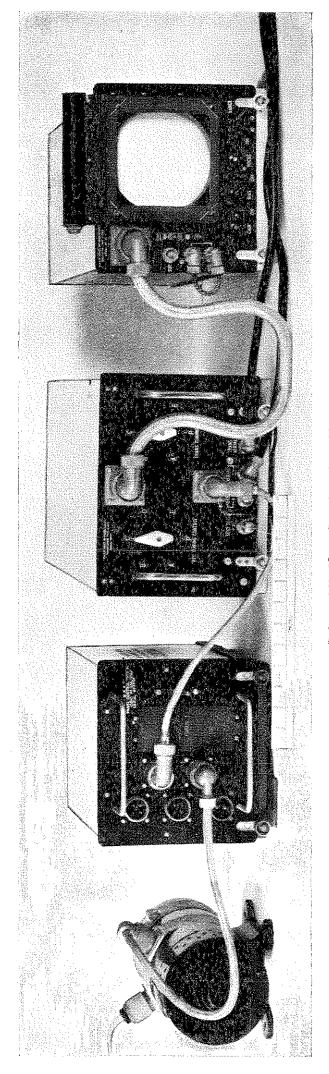
## REBECCA MK. IIB (AUST.)

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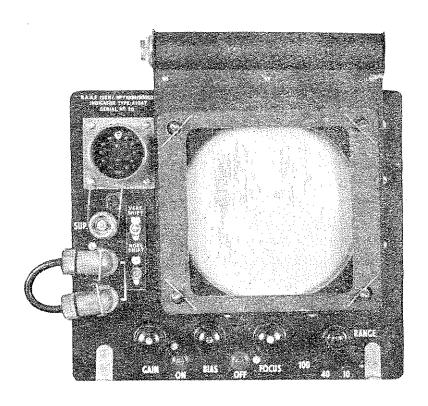
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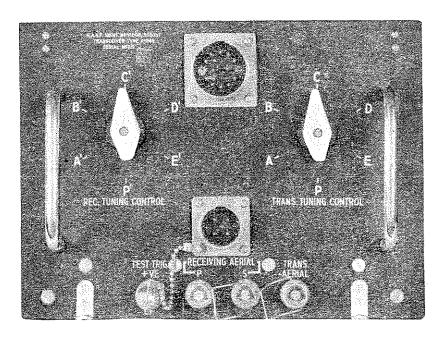
#### Introduction

- 1. Rebecca is an airborne Radar device to enable aircraft to home on to both ground and airborne responder beacons of the Eureka type. In addition, "air to air" homing is also possible when the equipment is operating on 176 megacycles and interrogating I.F.F. Mk. III.
- 2. A further function of the device is homing on to light transportable beacons for supply dropping in close support of ground troops. In this case the beacon is operated by ground forces. Another function of a similar nature occurs for marking "targets" on the ground, in this instance, however, the beacon is dropped by parachute.
- 3. As a navigation aid, Rebecca is used against fixed ground responder beacons of the Eureka type or Civil Aviation beacons operating on similar frequencies in the distance measuring network. When employed against such beacons the "200" megacycles band is used exclusively. These frequencies will be used internationally for the purpose, thus ensuring universal facilities for Rebecca equipments.
- 4. In its present form presentation is made on a cathode ray tube in a similar manner to A.S.V. Mk. II. When Rebecca is used against A.S.V. beacons some loss in range may be expected since the latter type beacons are horizontally polarized while Rebecca is vertically polarized. This applies also to "Walter", but it is anticipated that this device will soon be converted to vertical polarization.
- 5. Employment of the "200 megacycles band", as in the case of Rebecca, possesses the advantage of pre-selection of five spot frequencies within the band, both for transmitting and receiving. With this arrangement it is possible to transmit on one spot frequency and receive on another the four frequencies. When transmitting on one of the frequencies the beacon being interrogated will, of course, be tuned to receive on that frequency, but the transmitter of the beacon will transmit on the frequency to which the Rebecca receiver is tuned or frequency selected. Transmitting and receiving frequencies of the various beacons are known beforehand, thus the frequencies required to operate a particular beacon can be readily pre-selected by the navigator.
- 6. The reason for employing different frequencies for transmitting and receiving is important since complete eradication of ground returns results, thus enabling the operator to follow the beacon to zero miles on the indicator. Formerly, with A.S.V. equipment where transmitting and receiving on the same frequency was employed ground returns "swamped" the ten mile timebase making homing at the crucial moment difficult.
- 7. Conversely, Rebecca may be used as "search" equipment by transmitting and receiving on the same frequency. Its application in this field is limited, however.
- 8. Another advantage to be gained by using separate frequencies in the Rebecca-Eureka system is that it permits several ground beacons operating in close proximity without the undesirable effect of triggering unwanted beacons. Each beacon is set to receive and transmit on different frequencies to each other thus avoiding overloading of unwanted beacons.
- 9. Still another facility available to Rebecca is blind approach homing to R.A.F. BABS beacons operating in the 200 megacycles band. These beacons are mobile and positioned at the end of the runway in use. Indications on the Rebecca indicator take the form of dot and dash pulses of relative amplitudes transmitted from the BABS beacon. As in previous instances, separate frequencies are employed for transmitting and receiving, thus obviating ground returns. When Rebecca is used for this class of work the switch motor inside the receiver unit is stopped in order to obtain perfectly steady signals. A separate receiving aerial is used for BABS and is usually located on the fuselage well clear of the aircraft propellors in order to avoid propellor modulation of the signals. An electromagnetic switch remotely operated, selects either homing or blind approach aerials.

#### General Description

- 10. Rebecca Mk. IIB (Aust.) comprises a Transceiver Unit type A.1045, Indicator Unit type A.1047, a Control Panel type RD.21 or type 11 (according to the load requirements of other Radar equipment). Supply of power will be from an invertor operated from the 24 volt D.C. supply. The type of invertor used will again depend upon load requirements. An aerial system depending upon the type of aircraft will complete the installation.
- 11. Metal skinned aircraft of the Lincoln or Dakota types follow similar installation details so far as aerials are concerned, inasmuch as the receiving aerials are positioned one on each side of the fuselage near the cockpit and the transmitting aerials mounted beneath the "nose" of the aircraft.
- 12. Wooden aircraft of the Mosquito type follow a different installation since the characteristics of the hull of the aircraft do not lend to a suitable polar diagram. In these aircraft the receiving aerials are positioned on the wing tips and mounted upon a metal sheet to aid reflection. Aerials for this class of installation are quite different to those employed for metal skinned aircraft.





(Top) Indicator Type A.1047. (Lower) Transceiver Type A.1045.

- 13. The transmitting aerial consists of a quarter wave aerial and director whilst the receiving aerials for homing purposes are dipole and director combinations. For BABS receiving aerial a vertical quarter wave rod is used.
- 14. In all installations the receiver unit is to be positioned adjacent to the operator to enable control of the frequency selection switch.
- 15. On the front of the indicator unit, a scale calibrated in nautical miles appears beneath the glass visor. A four position switch selects the following ranges:—0-4, 0-8, 0-40 and 0-80 mile ranges. Other controls on the front panel are Brillaince, Focus and Gain, the latter control remotely regulating receiver gain by medium of connexions through the large interconnecting cable.
  - 16. For manipulation details of the equipment, the reader should refer to Misc. 551.

#### Summary of Rebecca Mk. IIB

Frequencies employed:-- 176 mega

176 megacycles, 214-234 megacycles.

Pulse Recurrence Frequency: - 350 cps.

Output Power (Peak):-

Average 300 Watts.

Pulse Width:—

2½ microseconds.

Power Consumption:

186.5 Watts.

#### Size and Weight of Components

	U	nit				Ident No.	Size	Weight
Transceiver type A. 1045 Indicator type A. 1047	 • •		••	 		Y10DB/500057 Y10OB/500007	104 × 184 × 75 84 × 18 × 75	35 lbs. 27 lbs.
Control Panel type RD21	 	٠,		 	٠,	 Y10LB/500009	$8\frac{7}{2} \times 10\frac{1}{2} \times 7\frac{7}{8}$	51 lbs.
Motor Alternator type MA6	 			 		 G5V/53422	$5\frac{1}{2} \times 11 \times 6$	25 lbs.

#### Aerials for Fuselage Installation

		Tve					,		Ident No.	
		1 y į							Ident No.	Frequency Range
Receiving (2) type 184 Transmitting (1) type 308							٠.,		Y10BB/2171	176 — 214 — 234 Megacycles
Transmitting (1) type 308	• •	• •	• •	• •	• •	: •		• •	Y10BB/2172	176 — 214 — 234 Megacycles

#### Aerials for Wing Tip Installation

And the second of the second o		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Ty	ре					Ident No.	Frequency Range
Director (1) type 54 Reflector (1) type 320 Dipole Aerial (1) type 5 Impedance Matching U	53			••	. :	 • •		••	Y10BB/6436 Y10BB/6438 Y10BB/6434 Y10AB/8550	176 — 214 — 234 Megacycles Starboard Wing
Director (1) type 53 Reflector type 319 Dipole Aerial type 53 Impedance Matching U	 Jnit typ					 	••	••	Y10BB/6435 Y10BB/6437 Y10BB/6434 Y10AB/6689	176 — 214 — 234 Megacycles Port Wing

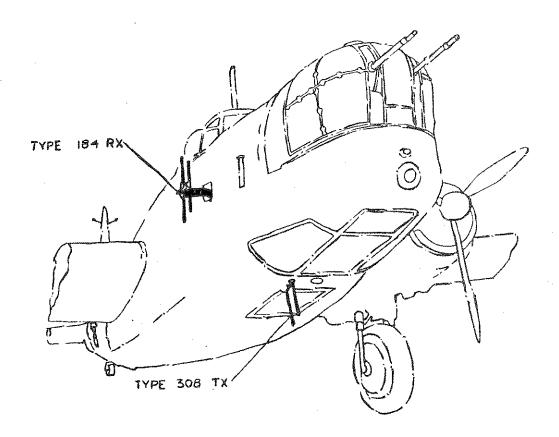
#### Test Equipment

- 17. The Test Set type RE.1 has been designed for testing all the various functions of Rebecca. It will provide the following information:—
  - (a) Receiver and Transmitter frequencies.
  - (b) Transmitter power output.
  - (c) Pulse recurrence frequency.
  - (d) Waveforms, pulse shape and pulse lengths.
  - (e) Range calibration.
  - (f) Squint tests and aerial directional properties.
  - (g) Receiver performance.

18. In addition to the main test set a separate oscilloscope is provided, also an aerial system mounted on a tripod for carrying out certain tests included in (a) to (g) above. Full technical and manipulation details will be found in R.A.A.F. Publication No. (to be issued later).

#### Maintenance

19. Complete maintenance instructions will be issued by Air Force Head-Quarters in the appropriate publication. Bench setting-up procedure for Rebecca Mk. IIB will be found in R.A.A.F. Publication No. (to be issued later) describing the use of Test Set type RE.1.



A Typical Rebecca Aerial Installation.

#### The Transceiver Unit A.1045

- 20. The function of the Transceiver type A.1045 is to transmit R.F. pulses for the purpose of triggering a radar beacon, to receive the response pulses from the beacon and to convert them into video pulses. These video pulses are then fed to the C.R.T. Indicator type A.1047 where they are displayed in such a manner that the range and approximate bearing of the beacon with respect to the aircraft, in which the Rebecca equipment is installed, can be determined.
- 21. The transceiver consists of five sub-units mounted on a main assembly chassis to form an integral unit. The five sub-units being Transmitter, Receiver, Pre-amplifier and Frequency Converter, Receiver I.F., Amplifier and Video Stages, Switch Unit Power Supply. Inter-sub-unit wiring is brought to a series of "M" type contacts on ceramic strips and these mate with male prongs mounted on the individual units. This wiring is contained in a channel running the length of the chassis. On the under side of the main chassis are mounted the marker pulse delay line, filament wiring filter chokes, by-pass condensers and bias developing network for receiver and local oscilator. See Fig. 5 for main chassis wiring.
- 22. External connexions are the A.C. power input 4 pin socket which is mounted at bottom centre of the front panel and a 12 pin socket mounted at the top centre of the front panel for the output connexions to the indicator type A.1047. Four pye connexions for port and starboard receiving aerials, transmitting aerial and positive test triggering pulse.
- 23. Two controls are fitted to the transceiver, viz., Transmitter Tuning Turret Control and Receiver Tuning-Turret Control. The transmitter tuning-turret and the receiver tuning-turret are mounted in their respective units, but when these units are assembled on the main chassis the turret shafts protrude through the fornt panel of the combined transceiver unit, the transmitter control at the right-hand side and the receiver control at the left.
  - 24. The transceiver works on the following six frequencies:—

Tran	ismitter	Re	eceiver
Frequency Band Designation	Frequency in Megacycles per second	Frequency Band Designation	Frequency in Megacycles per second
P	176	$\mathbf{P'}$	1 <i>7</i> 6
A	214	Α'	214
В	219	В'	219
$\mathbf{C}$	224	C'	. 2241
. D	229	D'	229
E	234	$\mathbf{E'}$	234

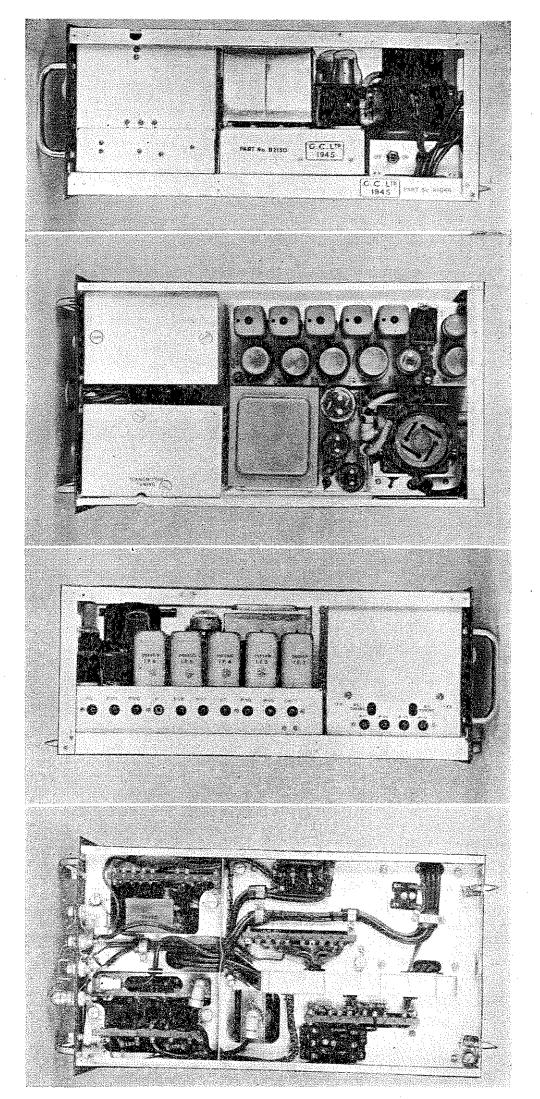
25. When the Rebecca equipment is being used in conjunction with Eureka, a combination of any one of the frequencies A, B, C, D, E and one of the frequencies A', B', C', D', E' may be used.

#### The Transmitter

General — Circuit Description — The Oscillator — Modulator and Pulse Forming Network —

Band Switching and Remote Control

- 26. The transmitter sub-unit contains an oscillator section consisting of two U.H.F. triodes operating in a push-pull circuit with Anode Lecher tuning (see Fig. 2 (A1)) and a modulator section consisting of a Thyratron valve with a pulse-forming network in its anode circuit (see Fig. 3A).
- 27. The function of the transmitter unit is to generate R.F. pulses of  $2\frac{1}{2}$  microseconds duration at a repetition frequency of 350 cycles per second. A secondary function is to develop voltage pulses which are used to trigger the zero range-marker pulse generator, to provide a means for synchronizing test equipment and for suppression of Mk. III I.F.F. equipment.
  - 28. The transmitter circuit may be divided into the following sections:—
    - (a) Oscillator Valves.
    - (b) Modulator Valve.
    - (c) Pulse-forming network and associated pulse transformer.
    - (d) Bandswitching control.
    - (e) Remote control.
  - 29. The operation of the above sections is as follows:—
    - (a) The oscillator U.H.F. triodes operate in a modified type of Colpitts circuit and provide an R.F. peak power output to the transmitting aerial, of not less than 300 watts over all frequency bands. The oscillator valves are anode modulated by a high voltage pulse developed by the modulator section. The occurrence of this pulse is controlled by a pulse generated in the timing-multi-vibrator at the same moment as the time base sweep commences. Thus the propagation



General Layout of Transceiver Type A.1045.

or the M.F. purses and the commencement or the trace occur annost simultaneously.

- (b) The modulator used is a Thyratron gaseous discharge valve operating with an anode voltage supply of 300 volts and a gri dbias of approximately 40 volts. This valve is triggered by the positive triggering pulse developed by the timing multi-vibrator. In the anode circuit of the thyratron is a network which in conjunction with a pulse transformer generates an anode modulating pulse each time the Thyratron is triggered.
- (c) The pulse forming network in the anode circuit of the Thyratron, in association with the pulse transformer, generates a 2½ microsecond pulse with a potential of about 2000 volts positive. This pulse in effect constitutes the anode H.T. supply for the oscillator valve and obviates the necessity of providing a transmitter high voltage supply additional to the 320 volt receiver supply. The secondary of the pulse transformer is tapped to provide a positive triggering pulse of approximately 150 volts to synchronize test equipment and to trigger a zero-range marker pulse generator located in the receiver I.F. amplifier sub-unit. The 150 volt triggering pulse can also be used for suppression of Mk. III I.F.F. equipment.
- (d) The transmitter is designed to operate on any one of six frequencies, viz., 176, 214, 219, 224, 229, 234 megacycles. To enable any one of these pre-set frequencies to be selected in flight, one of six condensers assembled in the form of a tuning turret is switched across the anode lechers. On the 176 megacycle band a small inductance is also connected across the anode lechers.
- (e) The H.T. supply to the transmitter is remotely controlled by press button ON/OFF switches mounted on the front panel of Indicator type A.1047.

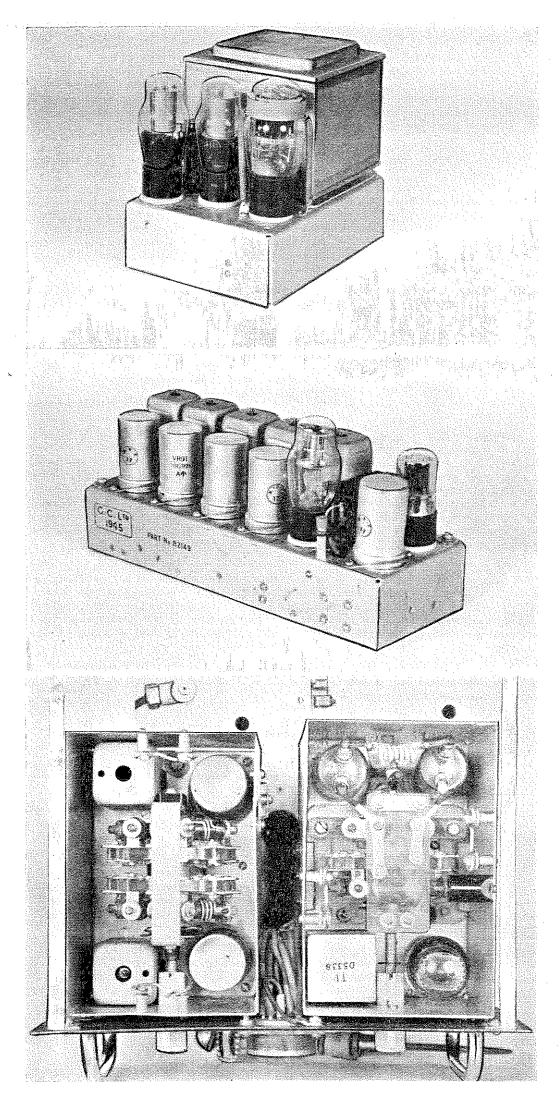
#### Circuit Description

- 30. Oscillator (Fig. 2(a)).—The oscillator has two U.H.F. triodes V13 and V14 operating in a push-pull circuit of a modified Colpitts type in which the tuned circuit is the "High Q" lecher line in the anode circuit. The cathodes of V13 and V14 as far as R.F. is concerned are isolated from ground by the high impedance chokes L33 and L38 and the circuit to ground is completed through inter-electrode capacities. The filaments are supplied with heating current through R.F. filter networks consisting of L34, L35 and L70 for V13 and L39, L40 and C77 for V14. The operation of this circuit depends upon the effects of the inter-electrode capacities of V13 and V14 for complete circuit diagram of the transmitter set (Fig. 4).
- 31. The extent to which oscillations are maintained by the effect of inter-electrode capacities is more easily understood by examining the operation of the oscillatory circuit on the highest frequency band, i.e., 234 megacycles. The equivalent circuit is shown at Fig. 2C. In this circuit the grid inductance L37 is not shown as the circuit will oscillate on 234 megacycles without this inductance. The function of the grid resistor is to fix the operating position on the grid-voltage/anode-current curve and therefore it has not been shown.
- 32. On Fig. 2d one-half of the circuit at Fig. 2c is shown. In this circuit that portion of the anode lecher line which forms the anode load of the valve shown in the circuit has been represented by a symbol, thus:—

ĄL

The inter-electrode capacities anode-grid (Cag), grid-cathode (Cgc) and anode-cathode (Cac) have been shown in the circuit. The cathode has been shown as open circuit with respect to ground because the cathode inductance is so designed that the cathode presents a high impedance with respect to ground.

- 33. The inter-electrode capacity, Cag, forms portion of the capacity that tunes the anode inductance, and the voltage developed across this capacity is split into two components appearing across Cac, and Cgc. The voltage across Cgc forms the feedback voltage which maintains oscillation.
- 34. On the lower frequency bands the inter-electrode capacities, by reason of losses are not capable of sustaining oscillations, and so a small inductance, L37, has been inserted in the grid circuit. On the 176 megacycles band it is necessary to add a further inductance, and this is accomplished by switching the inductance L36 across the anode lechers on this band only.
- 35. The anode lechers are tuned to any one of six frequencies by action of a six position turret which connects any one of six trimming condensers C71-2-3-4-5 across the anode end of the anode lechers. The inductance L36 is shorted by the action of this turret on all frequency bands except P frequency.
- 36. Transfer of R.F. energy from the oscillator circuit to the coaxial transmission line is achieved by a pick-up loop spaced  $\frac{1}{8}$  in. distant from the anode lechers. This spacing of  $\frac{1}{8}$  in. is critical to ensure that not less than 300 watts R.F. power is transferred to the transmission line overall frequency bands.
- 37. During the quiescent period between mutli-vibrator pulses, H.T. is not applied to the anodes of V13 and V14. To cause the valves to oscillate a H.T. pulse is developed



Transceiver Type A.1045 showing Brick Construction of the Power Supply (top).

I. F. Strib (middle) Transmitter and R. F. Head (losser)

across the secondary winding of the pulse transformer 11 and 100 v13 and v14, this pulse lasts for approximately  $2\frac{1}{2}$  microseconds, and at the cessation of this pulse the oscillator returns to its normal non-oscillatory state. The R.F. pulses generated are of the same duration and repetition frequency at the modulating pulses.

- 38. Modulator and Pulse-Forming Network.—The modulator and pulse-forming network (Fig. 3a) consists of a gaseous discharge valve V15, a pulse shaping network, L42-3-4, C78-9-80 in the anode circuit of V15. The primary of T1 forms the inductive load through which the network is discharged to form a 20 volt pulse. The pulse in the primary of T1 develops an oscillator-modulating pulse of approximately 2000 volts positive in the secondary winding. A tapping on the secondary of T1 provides an additional voltage of 150 volts  $\pm$  20% and this is used for synchronizing test equipment and also to trigger the gaseous discharge valve used as a zero range marker pulse generator.
- 39. Fig. 3b shows the circuit of the modulator section with V15 de-ionized and the pulse network charging through CK1. The circuit in effect becomes a series resonant circuit; the values of L42-3-4 are smaller in comparison with CK1 and are not shown. In the diagram L is CK1 and C is C78-9-80, the resonant frequency being 175 c.p.s. which is half the P.R.F. of the pulses generated by the multi-vibrator.
- 40. In a series resonant circuit if a voltage pulse of short duration is impressed at the points A, A' the circuit wil be forced into damped oscillations. In Fig. 1c the frequency is 175 cycles per second. The maximum voltage reached by the peak of the first cycles is theoretically twice the exciting voltage but circuit losses will prevent the theoretical maximum being reached.
- 41. In Fig. 3c at the instant the thyratron is triggered by the positive pulse from the multivibrator the voltage across C is almost 600 volts.
- 42. When the thyratron fires the circuit is as shown in Fig. 3d. The charged line L42-3-4, C78-9-80, is in effect an open ended transmission line charged to a potential of approximately 600 volts. The impedance of CK1 is so much larger than the characteristic impedance of the network (33 ohms) that this end of the line may be considered to be effectively open.
- 43. If a transmission line is charged to a voltage E and is connected across a load resistance RL the line acts as a voltage source E, in series with a resistor RO when RO is the characteristic impedance of the line. Therefore if RL = RO the voltage across RL
- is  $\frac{E}{2}$ . In Fig. 3e RL is the impedance reflected into the primary of T1, RO is the charac-

teristic impedance of the pulse shaping network and E is approximately 600 volts. The line is switched to its load resistance RL when a positive trigger pulse drives the thyratron into conduction. The voltage drop across V15 is only 15 volts and therefore almost all of the available voltage is applied across RL.

- 44. The pulse which is actually impressed on the grid of the thyratron is a narrow pulse, the duration of which is constant irrespective of the setting of the range switch in the indicator. This is achieved by differentiating the triggering pulse from the indicator by the time constant of C81, R59, R60. The resistor R60 also serves to limit the grid current of the thyratron.
  - 45. When the line is switched to discharge through RL a voltage of  $\frac{E}{2}$  will appear

across RL and the voltage at A will drop to  $\frac{E}{2}$  causing a wave of value  $\frac{-E}{2}$  to start

down the line and be reflected back from the open B in phase. When the reflected wave

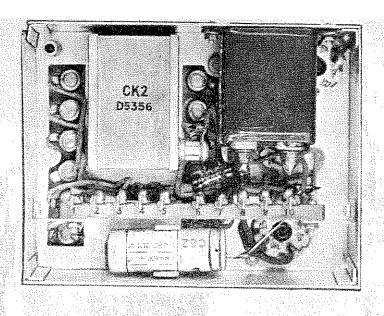
returns it will add a potential of  $\frac{-E}{2}$  to the voltage at A, reducing it to zero, and since

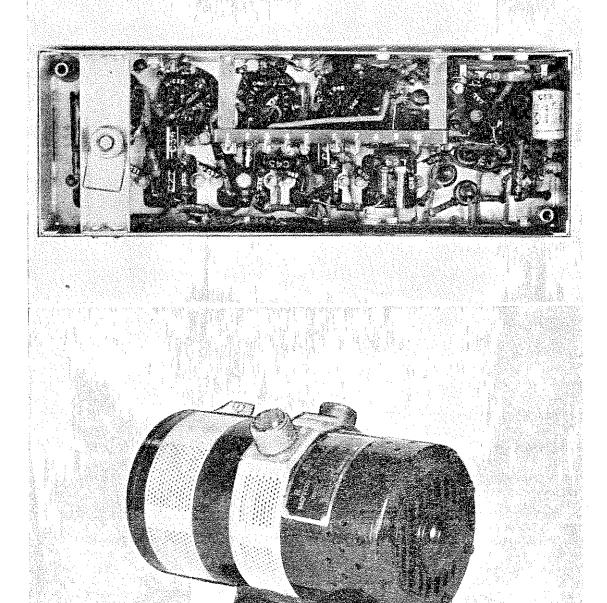
the load RL matches the line there will be no more waves on the line. Hence there will

be a pulse of voltage equal to  $\frac{E}{2}$  across the load resistor RL and the duration of the pulse

will be the time taken for the voltage wave to travel the length of the transmission line and return.

- 46. The action of the transmission line is to abruptly begin to discharge through RL at a constant rate. If the network consisted of only C78-9-80 the discharge curve would be exponential. However, by using a well designed artificial line which contains both inductance and capacity the discharge rate can be held to a substantially constant value as long as the line is discharging. As the line becomes completely discharged, the anode voltage of V15 falls below the ionization point and the valve becomes non-conductive, since the choke CK1 momentarily prevents the supply of sufficient current to maintain the anode voltage. After the valve has ceased to conduct the line again charges up to potential of nearly 600 volts at the time the thyratron fires again.
- 47. In Fig. 3e, E is approximately 600 volts, RL is 33 ohms, RO = 33 ohms, and delay of line = 1 microsecond. Thus theoretically, a  $2\frac{1}{2}$  microsecond pulse of 300 volts should be obtained but owing to losses, a  $2\frac{1}{2}$  microsecond pulse of approximately 280 volts is ob-





(Top) Sub-Chassis View of Power Unit. (Middle) I.F. Strip.

former is approximately 2000 volts and this is the modulating pulse applied to the anodes of V13 and V14.

- 48. Bandswitching Control.—The anode lechers of the oscillator valves are tuned to any one of the six frequencies by a six position turret carrying six trimmer condensers. As the turret is rotated the condensers are switched, in sequence, across the lechers by a series of "knife blade" contacts and wiper contacts. The ends of the condensers are connected to the knife blades and the anode lechers are connected to the wiper springs. A metal disc, out of which a segment has been cut, is fitted to the turret and this makes contact with a pair of wiper springs connected to the inductance L35 except on the 176 megacycles band when the bridge is removed from the inductance since the gap in the shorting disc is set to coincide with this position.
- 49. The high tension to the transmitter, i.e., the anode of V15, is remote controlled by two spring loaded press button ON/OFF switches mounted on the indicator front panel.

#### CHAPTER 2

#### Receiver

General — Circuit Description — R.F. — Amplifier — Local Oscillator and Mixer — I.F. Amplifier — Detection — Video Amplifier — Zero Range — Marker Pulse Generator Cathode Follower — Switch Motor — Setting Up the Receiver — Monitoring Points — Test Voltages and Continuity Check

#### General

- 50. The function of the receiver is to provide a means of admitting the response pulses picked up by the receiving aerials and to transform these R.F. pulses into voltage pulses suitable for display on the screen of a cathode ray tube. A further function is to generate a voltage pulse to act on the C.R.T. trace in such a manner that it provides a zero range marker.
- 51. The receiver circuit is basically a conventional superheterodyne and consists of the following sections:—
  - (a) R.F. unit consisting of a grounded grid R.F. stage, local oscillator, mixed and 1st I.F. amplifier stage.
  - (b) Amplifier sub-unit consisting of I.F. channel, detector, video amplifier and cathode follower.
  - (c) Zero range marker pulse generator and associated delay line.
  - (d) Switch unit.
  - (e) Tuning turret.
- 52. The R.F. frequency conversion circuits of the unit are designed so that an intermediate frequency of 30 megacycles is obtained from any one of the six frequency bands to which the receiver is required to tune.
- 53. The requirements of the R.F. amplifier stage of the R.F. unit are that it should provide for effective aerial matching and even gain on all six frequencies with the minimum development of random noise. A further requirement is that R.F. amplifier should act as a frequency rejector circuit with respect to the intermediate frequency.
- 54. A grounded grid triode buffer amplifier is used to fulfil these requirements inasmuch as:—
  - (a) The input resistance of this type of amplifier is low and effectively matches the aerial load, and the resonant frequency curve of its input circuit is reasonably flat over the six frequency bands.
  - (b) One of the causes of random noise voltage developed in R.F. amplifiers is partition noise caused by the irregularity of the division of current between anode and screen. This noise is inherent in pentodes and tetrodes. The reduction in noise level by using a grounded-grid triode in the input stage instead of a pentode is approximately 4 db.
- 55. The anode circuit of V2 (see Fig. 6) is tuned to any one of the six frequencies by a turret carrying six pre-tuned inductances. The local oscillator is tuned by a second bank of six pre-tuned inductances carried in the tuning turret. The local oscillator frequencies corresponding to the six input signal frequencies are:—

0 0011011101111115	0 11-0 0111 1111/	ar organia in equien	creo core.		
Frequency Band	Fre	quency in megacye	cles Locai	Oscillator Frequency	
Designation		per second	i11 1	negacycles per second	
$\mathbf{P'}$	٠,	176		206	
A'		214		184	
В'		219		189	
C'	• •	224		194	
$\mathrm{D}'$		229		199	
E'		234		204	

On P' band the local oscillator frequency is 30 megacycles above that of the corresponding input frequency in order that the physical dimensions of the local oscillator inductance be kept as small as practicable.

56. A five stage 1.F. amplifier channel (see Fig. 7) is used with an intermediate trequency of 30 megacycles and an overall bandwidth of 2.2 megacycles for 3 db. down. To achieve this bandwidth, stagger-tuning of the IFT's has been adopted in preference to isochronous tuning, the reason being that higher overall gain is possible with stagger tuning than that obtained with isochronous tuning for the same bandwidth. In addition to the staggering of the I.F.T. tuning the bandwidth is governed by the "Q" of the tuned circuits. This has been obtained in this case by the values of the anode load resistors used. The I.F. grid inductances are tuned to the following frequencies:—

- 57. The output from the I.F. channel is rectified by a diode detector. The rectified video signals are then amplified by the video amplifier V10 and fed to the inidcator through a cathode follower V11.
- 58. Receiver gain is controlled by earthing the grids of the I.F. amplifier valves through the respective tuned circuit and returning the cathodes of the first three I.F. stages to a point at a variable potential above earth. The gain control is a 2000 ohm potentiometer mounted on the front panel of the indicator. Connexion between this control and the valve cathodes is by the shielded cable connecting the transceiver and indicator units.
- 58. The optimum flying height of an aircraft for dropping supplies is 500 feet. To provide an indication that the aircraft flying at this height is directly above the Eureka a marker pulse is displayed on the C.R.T. to denote the position which the Eureka signal will occupy at this instant.
- 60. The zero marker pulse generator is a gaseous discharge valve with a load resistance in its cathode. The positive pulse developed across this resistor is fed to the grid of a cathode follower. This cathode follower is one-half of a twin-triode, the other half of this valve is used on the cathode follower for the video amplifier. The cathodes of both halves are joined, thus the video signals and the marker pulses are combined.
- 61. To give a bearing sense to the received signals a switch motor is used to connect the port and starboard aerial feeders alternatively to the receiver input about 30 times per second and is synchronized with the aerial switching to connect the receiver output to the cathode ray tube port and starboard deflection plates respectively.
- 62. Tuning of the input circuit of the mixer valve and the anode circuit of local oscillator to any one of the six frequency bands is accomplished by a two-bank six position tuning turret similar in construction and operation to the transmitter tuning turret. In place of the pre-set trimmer condensers, however, are two blanks each of six inductances. These inductances are adjustable, within limits, by means of brass tuning slugs. To ensure stability, the inductances are wound on glass formers, the tuning slugs being held firmly inside the formers.

## Circuit Description R.F. Unit (Fig. 6)

- 63. The received signal is impressed on the cathode of the grounded-grid triode amplifier V2 through blocking condenser C7 and condenser C8, which bypasses R5. The cathode of V2 is held above earth potential for R.F. voltages by choke L9 and the D.C. path to earth is through bias-resistor R5. The output from V2 is impressed on the tuned input circuit of V3. This circuit consists of C11, one of the inductances L11-12-13-14-15-16, C12 and the input capacity of V3. The H.T. supply to anode of V2 is through anode load L10 which is bypassed by C10, decoupling resistor R7 and metering resistor R6. One filament connexion is earthed and the other is connected direct to the filament supply.
- 64. The tuned circuit of the local oscillator V1 consists of one of the inductances L1-2-3-4-5-6 of the receiver turret and the inter-electrode capacity Cag of V1, the resonant frequency being 206, 184, 189, 194, 199 or 204 megacycles, depending upon the setting of the tuning turret. Oscillations are maintained by the feedback voltage developed across C1 and Cgc of V1. The high tension supply to anode of V1 is through anode load R2, decoupling resistor R3 and metering resistor R4 and the load R2, decoupling resistor R3 and metering resistor R4 and the network is decoupled by C6. One filament connexion is earthed and the other is fed through R.F. choke L8.
- 65. VI does not oscillate continuously but is normally biassed to quiescence and brought to an oscillatory condition for the duration of the time-base sweep. The grid of VI is returned to the junction of R55 and R56. This point is approximately 12 volts negative with respect to earth, and is also connected to the modulator pulse line through limiting resistor R54 and blocking condenser R53. The positive triggering pulse is used to overcome the bias on VI and cause it to oscillate for the duration of the time-base sweep. This pulse is fed to the grid of VI through filter choke L7 and grid resistor R1. R.F. bypassing is effected by C2 and C3.
- 66. The local oscillator frequency is fed through coupling condenser C5 to the grid of the mixer valve V3 where it mixes with the signal frequency. The output from V3 is fed to the 1st I.F. stage through coupling condenser C17. The H.T. supply to V3 is through anode load R11 and metering resistor R10, the anode is by-passed by C15, and the anode load resistor by C14.
- 67. V4 is a pentode operating as the 1 I.F. amplifier. The grid of V4 is tuned to 30 megacycles by permeability tuned inductance IFT.1 and resonates to a beat frequency of 30 megacycles per second derived from the difference of the local oscillator frequency and

the signal frequency. The output of V4 is coupled by C23 to a co-axial line connecting the R.F. unit to the input terminal of the amplifier unit. The anode high tension of V4 is obtained through anode load decoupling resistor R14, metering resistor R13, and decoupled by C20. The screen voltage is obtained from the junction of R14 and R15 and bypassed by C24. The suppressor grid is connected to earth and the cathode is returned to earth through the gain control and bypassed by C18 and C21.

68. The high tension and filament supplies for the R.F. unit are developed in the transceiver power-upply unit. The + 320 volt high tension enters the R.F. unit via pin 8 of the "M" type connector strip. R.F. filtering is effected by L28 and C64. Inside the R.F. unit the H.T. line is bypassed by C16 and C19. One connexion of the filament L.T. supply is provided by earthing one side of the filament L.T. supply is provided by earthing one side of the filament winding on T2 to earth and earthing one side of the valve filament connexions. The other filament connexion is via pin 5 on the connector strip and R.F. choke L27. Inside the R.F. unit it is bypassed by C9.

Circuit Description — Amplifier Sub-Unit (Fig. 7)

68. The output of the R.F. sub-unit is fed to the grid circuit of the second I.F. valve V5. The first I.F. valve V4 is located in the R.F. sub-unit. The grid circuit of V5 is tuned to 32 megacycles by I.F.T.2.\* The anode voltage is supplied from the sub-unit H.T. through metering resistor R18, bypassed by C30, decoupling resistor R19, bypassed by C31, and the anode load R17 and R20. The screen potential is obtained from the junction of R18 and R19 and bypassed by C25. The cathode is returned to a point at a variable potential above earth through R16 and the gain control, located in the indicator. The minimum bias is developed across the cathode resistor R16 and the cathode is bypassed to earth by C26. The suppressor and one side of the filament are earthed, the other filament connexion is through a filament choke L18, bypassed by C29, to the sub-unit filament supply.

70. The anode of V5 is coupled to the grid circuit of the third I.F. amplifier V6 through blocking condenser C32. Circuit constants in this stage are identical with the second stage with the following exceptions:—

- (a) The inductance of IFT3 is lower than that of IFT2 and the grid circuit is resonant at 28.25 megacycles.
- (b) The anode load resistors R22, R25 are of lower resistance than the load resistors of V5.
- 71. The fourth and fifth stages, i.e., V7 and V8, are similar to those of the second and third stages, except that:—
  - (a) Fixed bias is obtained by returning the cathodes to earth through R26 and R31, respectively.
  - (b) The V7 anode load resistors R27 and R30 are the same values as V5 anode load ,R17 and R20.
  - (c) The anode load resistors R32, R35 of V8 are of higher resistance value than the anode loads of the preceding stages in order to raise the effective value of the "Q" of IFT6 above that of IFT2, IFT3, IFT4 and IFT5.
  - (d) The grid circuit of V7 is tuned to 32 megacycles an dthat of V8 to 28.25 megacycles.

73. The diode V9 is used to rectify the output of the I.F. amplifier channel. The input circuit of the diode is tuned to 30 megacycles by permeability-tuned inductance I.F.T.6. The rectified output from V9 is developed across the diode load resistor R36. Portion of the diode output is developed across the metering resistor R37. To prevent intermediate frequencies appearing in the video output, an I.F. filter consisting of L22 and C53 is included in the anode circuit of V9. One side of the filament of V9 is earthed and the other side is fed through L23 and bypassed by C52.

74. The output from V9 is fed through C56 to the grid of the pentode video amplifier V10. The screen dropping resistor R40 is much lower in value than the anode load resistor R43. This results in V10 operating with a higher screen potential than anode potential and a steep grid-voltage anode-current curve with sharp cut-off characteristics. The value of C57 is such that the static operating condition of V10, is near the top of the straight portion of the vg:ia curve. The diode V9 conducts on the negative half of the waveform impressed on its cathode and the subsequent excursions of its anode are impressed on the grid of V10, driving this valve towards cut-off and resultin gin a positive going video signal output. The anode voltage of V10 is supplied from the sub-unit H.T. through metering resistor R41, decoupling resistor R42 and anode load resistor R43 which is bypassed by C58. The screen voltage is supplied through R40 from the junction of R42 and R43. The junction of these resistors is bypassed by C58, and the screen is bypassed by C57. The suppressor and one side of the filament is earthed, and the other side of the filament is connected directly to the L.T. supply. The output from V10 is coupled to the grid of one section of a twin triode V11, each section of which is connected as a cathode follower. The input to the video section of V11 is through C59 and grid damping resistor R45.

<sup>\*</sup> It should be noted that additional factors influencing the resonant frequency of the input circuit of each I.F. amplifier stage are (a) the grid-cathode capacity of the valve (b) the distributed capacities of the interstage wiring and (c) capacity of the output circuit of the preceeding stage. Further, with respect to V5, the dominant capacities are the distributed capacity of the co-axial cable connecting the R.F. and amplifier sub-units, and the capacity Cgc of V5.

75. The gaseous discharge valve V12 is normally held in a non-conducting state by a grid potential of aproximately —40 volts, which is developed in the power unit and brought to the grid of V12 through pin 4 of the ten pin connecting strip and R51. While V12 is in this non-conducting state, a pulse-forming network L25, L26, C61 and C62 in its anode circuit is charged to approximately 200 volts from the junction of the voltage divider R49 and R50. The valve is fired by a +150 volt pulse which is developed in the transmitter pulse transformer, T1, at the instant the transmitter is modulated. The +150 volt pulse is applied to the grid of V12, through differentiating circuit C60 and R53, causing it to conduct and connect the cathode resistor R44 across the charged pulse forming line and so discharge it. The retardation time of the pulse line is very short and a correspondingly short pulse is developed across R44. The resistor R53 serves to limit the grid current of V12. The cathode end of the resistorR44 is directly coupled to the grid of one-half of V11. The two cathodes of V11 are connected to the common cathode resistor R46 and thus the output from each section of V11 appear across this resistor. The output from the common cathodes of V11 is taken via pin 10 of the connecting strip to the input of the video switching bank of the switch motor whence it is fed to the appropriate cathode ray tube deflection plates .

75. The firing of V12 is not coincident with the pulsing of the transmitter, but is delayed for approximately  $2\frac{1}{2}$  microseconds by delay line L29, L30, L31, L32, C66, C67, C68 and R57 mounted on the underside of the main chassis. This delay line is an artificial transmission line simulating the path of a transmitted pulse from a Rebecca transmitter, in an aircraft flying at 500 feet, to a Eureka, the time taken for the Eureka to respond, the return path of the Eureka pulse and finally the delay in the Rebecca receiver. Thus on the C.R.T. screen, the zero-range marker pulse will provide a calibrating marking to indicate the position at which a "blip" from a Eureka will appear when the aircraft flying at 500 feet is directly above it.

76. The high tension and filament supplies for the amplifier unit are developed in the transceiver power supply unit. The  $\pm 300$  volt H.T. is brought to the amplifier unit via pin 6 of the connector strip. Filament wiring is similar to that of the R.F. unit, one filament connexion being earthed, and the other filament connexion is via pin 3 of the connector strip. This lead is bypassed by C65 mounted on the main chassis.

77. Monitoring points have been provided for determining the operating condition of various circuit elements and are set out in the circuit diagram attached.

#### Alignment of Rebecca Receiver

78. Couple I.F. signal generator to mixer grid. (Signal generator output to be terminated in 80 ohm load.) The oscillator plate lead is to be lifted off the valve. All leads are to be as short as possible, and shielded as near as possible to the connecting point. This is most important. The earth connexion should be near the mixer grid.

79. Set the I.F. signal generator to 30 megacycles. Adjust the attenuator until about ½ scale reading is obtained on the meter (0-1 m.a.) connected across the Receiver output monitoring terminal (meter to be approximately 100 ohm resistance — not critical).

The I.F. Stagger Frequencies are as follow:-

```
Transformer I.F.1 — 30.0 megacycles 

,, I.F.2 — 32.0 ,, I.F.3 — 28.25 ,, I.F.4 — 32.0 ,, I.F.5 — 28.25 ,, I.F.5 — 28.25 ,, I.F.6 — 30.0 ,,
```

The procedure is as follows:-

- (i) Set signal generator to 30 megacycles.
- (ii) Tune I.F.1 and I.F.6 for maximum output on meter.
- (iii) Set signal generator to 32 megacycles.
- (iv) Tune I.F.2 and I.F.4 for maximum output on meter.
- (v) Set signal generator to 28.25 megacycles.
- (vi) Tune I.F.3 and I.F.5 for maximum output on meter.
- (vii) Repeat (i) to (vi).
- (viii) Tune signal generator across the band to see whether double peaks occur. If so, it is usually possible to get rid of this by changing valves. This is only necessary if the double peak is very marked.
- (ix) Find the actual peak by tuning signal generator. If not on 30 megacycles adjust the I.F.6 until this is so. In doing this, make the adjustment to the trimmer first, then check again by tuning signal generator. Do not set signal generator to 30 megacycles and peak, as this introduces errors. At this stage, the sensitivity should be —58db. for ½ scale reading on meter (i.e., approximately 5 v.output) (0-1 m.a.).

#### I.F. Bandwidth for 3 db. down

- (i) Set signal generator to 30 megacycles.
- (ii) Set attenuator to give ½ scale on meter.
- (iii) Turn attenuator 3 db. up.
- (iv) Tune signal generator  $\pm$  to get  $\frac{1}{2}$  scale again and note readings, which should be approximately  $\pm$  1.4 megacycles.

80. If unit is not operating, overload with signal generator and tune over band with meter on monitoring point for each stage. A dip should be noted if stage is working correctly when tuned through its particular stagger frequency.

#### R.F. Unit

Select "A" band.

Loosely couple 30 microseconds signal generator into input to Transceiver I.F.2 —no direct connection required.

Directly couple R.F. signal generator to one aerial terminal and stop switching motor.

Set signal generator to "A" frequency.

Tune "oscillator" and obtain the following on indicator:-

(a)



When exactly on frequency beat note shows thus:-

(b)



- 81. This will change when tuning tool is taken out, hence the adjustment must be made so that the beat note appears as at Fig. b when tuning tool is removed.
- 82. Then switch off I.F. signal generator and peak "R.F." adjustment to meter in receiver output and repeat until no interaction is present. Proceed similarly for all other bands.

#### Overall Sensitivity

Signal = double noise on output meter.

-85 db.

-65 lb. for  $\frac{1}{2}$  scale reading, always with switching motor off.

Noise level is to be as convenient.

Overall bandwidth 2.2 megacycles should be obtained for 3 db. down.

Note.—These precautions to be observed in all this procedure:—

- (1) Gain control must be full on.
- (2) Switching motor must be off.
- (3) Indicator is to be on 100 mile range.
- (4) Input is to be 80 v. exactly. (The above figures taken on 1250 cycles per second but it probably does not make much difference.)
- (5) Keep carrier adjustment on signal generator always on 0.1 volt when moving signal generator frequency control, as this changes signal generator frequency slightly.

### Transceiver Power Supply (Fig. 8)

#### General

- 83. The Transceiver-power supply sub-unit develops the high tension voltages for the transmitter, receiver and the indicator (excluding the C.R.T.) and the filament voltages for the transmitter and receiver.
- 84. The primary source of power is a motor driven alternator, type MA6, having an output of 80 volts and 2000 cycles per second. The power supply sub-unit is designed to operate from this source of power and also, by a tap on the primary of the transformer T2, an input voltage of 115 volts can be used.

- 85. Three secondary windings are wound on the transformer 12.-
  - (a) A centre tapped high voltage winding which in conjunction with the rectifier valve V18 and associated filter circuit develops the 320 volt high tension supply.
  - (b) A 5 volt winding for the filament of the rectifier.
  - (c) The third winding develops 6.9 volts for the oscillator valve filaments, and a tap on this winding provides 6.3 volts for the filaments of the remainder of the transceiver valves.
- 86. The high tension centre tapped winding, in conjunction with V18, forms a full wave rectifier circuit and develops the high tension voltage for the transmitter, receiver and indicator valves, with the exception of the cathode ray tube, which has its power supply incorporated in the indicator, type A.1047 (see Fig. 9). The high tension supply to the transmitter, receiver and valves V1, V3, V5, V7 of the indicator is filtered by CK2 and C82, C83, C84, plus a R.F. bypass condenser C85. The voltage at the output of the power supply sub-unit is 320 volts positive and is distributed to the receiver by the intersub-unit cabling and to the transmitter control switches and indicator by pin No. 7 of the 12 pin plug, which is in turn connected to the indicator by the 11 core shielded cable. The transmitter high tension is taken from the control switches located in the indicator through the shielded cable and pin No. 8 of the 12 pin socket.
- 87. The centre tap of the high tension secondary is returned to earth through R62 and the resulting voltage drop of 40 volts across this resistor is used for bias purposes in the transmitter and receiver sub-units.
- 88. The valves V16 and V17 are used to regulate the supply to the anodes of the multi-vibrator and pulse amplifier valves of indicator, type A.1047. The regulation of this supply is sufficient to prevent motorboating in these stages and further, by keeping this supply voltage to exactly 300 volts eliminates changes in P.R.F. caused by voltage fluctuations. This supply is not filtered by the CK2, C82-83-84 combination, but is smoothed by CK1 located in the indicator unit. The resistor R61 in conjunction with CK1 provides the necessary series resistance to ensure correct operation of the regulator valves V16, V17
- 89. The various voltage outputs from the power supply sub-unit are brought to a 10 pin connecting strip, which mates with a 10 pin "M" type connecting strip on the main chassis assembly, and are distributed to the respective sub-units. One side of the power input line from the 4 pin power input socket is connected to pin 9 of the "M" type connecting strip, the other connexion being to pin 7 or 8 of this strip for 115 volts or 80 volts input, respectively.

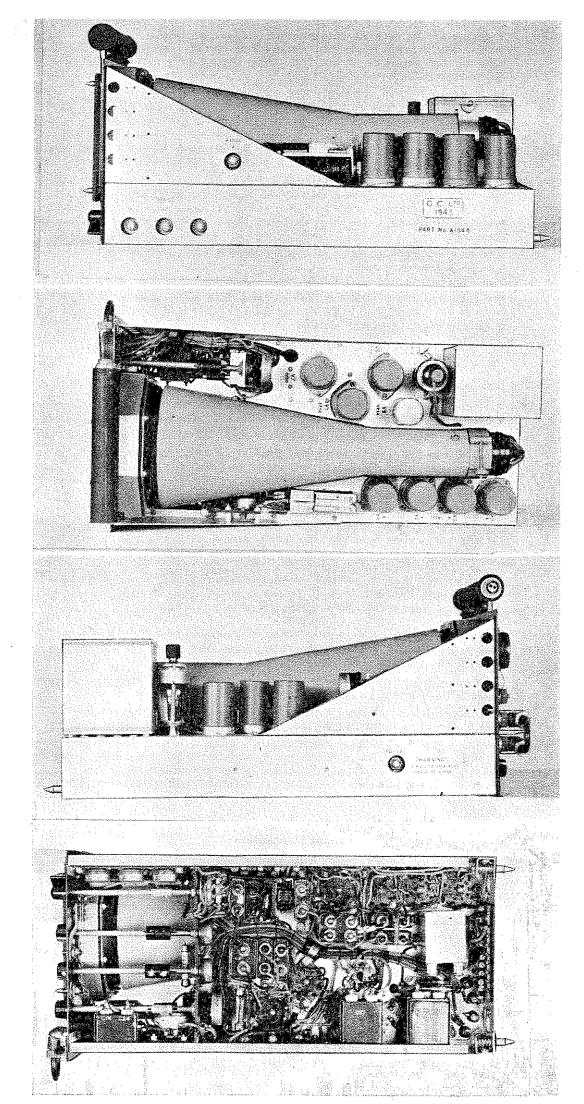
#### CHAPTER 3

## Indicator Type A.1047 (Fig. 9)

General — Circuit Description — Multi-vibrator — Time Base Circuit — Development of Shift Voltages — Cáthode Ruy Tube and Power Supplies — Remote Control and Relay for Transmitter High Tension

## General

- 90. The function of the indicator is to provide a means of display for determining the range and approximate bearing of the ground beacon with respect to the aircraft in which the Rebecca equipment is installed. A further function of the indicator is to provide a pulse which is used to control the pulsing of the transmitter, which in turn controls the generation of a zero range marker pulse for impression on the indicator trace.
  - 91. The indicator circuit may be divided into the following sections:—
    - (a) Multi-vibrator.
    - (b) Time base circuit.
    - (c) Shift voltage.
    - (d) Cathode ray tube.
    - (e) Pulse amplifier.
    - (f) Remote control of transmitter high tension.
    - (g) Cathode ray tube power supply.
  - 92. The operation of the above sections is as follows:—
    - (a) The multi-vibrator circuit is the timing control for the whole sequence of events occurring in the Rebecca-Eureka system. Two square pulses, one of which is negative and the other positive, are generated simultaneously at a repetition frequency of 350 cycles per second. The duration of each pulse is varied according to the particular range setting of the indicator. The positive pulse is fed to the grid of the cathode ray tube and "lights up" the trace for the duration of the sweep. The negative pulse is used to control the time base valve, and a portion of this pulse is also fed to the pulse amplifier, the output of which serves to trigger the transmitter modulator and simultaneously suppress the receiver.



Conoral Layout of Indicator Tabo A 1017

- (b) The time base circuit develops a saw-tooth waveform which is applied to the Y plates of the cathode ray tube producing a vertical trace which is approximately linear with respect to time. Four speeds are provided for the time base so that the time of the full sweep corresponds to ranges of 4, 8, 40 or 80 nautical miles.
- (c) In order to control the centering of the trace and the position of its commencement adjustments are provided for the variation of the potential on one each of the X and Y plates.
- (d) The cathode ray tube is used to provide "A" scan presentation, that is, the trace commences at the bottom centre of the screen and travels vertically, while the echoes are displayed as horizontal deflections of the trace.
- (e) The function of the pulse amplifier valve is to amplify and phase-change portion of the negative pulse developed by the multi-vibrator so that it can be used as a triggering pulse for the transmitter modulator. The output from the pulse amplifier is fed to a cathode follower which provides a low impedance output.
- (f) The transmitter high tension control switch is located in the indicator and acts as a remote control.
- (g) The indicator power supply circuit develops filament voltages for the cathode ray tube and other indicator valves, and also high tension voltage for the cathode ray tube. The high tension for the other indicator valves is developed in the transceiver power supply.

#### Physical Details of the Indicator Unit

- 93. The external connections consist of:-
  - (a) A twelve pin socket, mounted on the top left hand corner of the front panel, provides the input terminal for the shielded cable from the transceiver unit.
  - (b) Three pye sockets mounted on the left hand side of the front panel.
    - (i) The top pye socket furnishes the output terminal for the negative suppression pulse. This was originally intended for I.F.F. Mk. III suppression but a suppression modification now incorporated in these units requires the use of a positive suppression pulse as obtainable at the + triggering pulse socket of the transceiver.
    - (ii) The centre and bottom pye sockets are the starboard video output for the transceiver and the starboard video input to the indicator. The "video out" socket is connected internally to the starboard video lead contained in the shielded cable connecting transceiver and indicator units. The video "in" and video "out" sockets are normally bridge dby a short length of co-axial cable which is removed when it is required to connect the output from a calibrator to the video input socket.
- 94. The operating controls and adjustments are mounted as follows:—
  - (a) The control knobs for the gain, bias, focus and range controls are mounted beneath the cathode ray tube.
  - (b) The two push button transmitter remote control ON/OFF switches are mounted beneath the control knobs.
  - (c) Two screwdriver adjusted potentiometers constituting the vertical and horizontal deflection adjustments are mounted to the left of the cathode ray tube.
  - (d) On the right hand side of the indicator chassis are four screwdriver adjusted potentiometers for range adjustments and on the left hand side of the chassis is the screwdriver adjusted trace calibration potentiometer. When the dust cover is in position these controls are accessible through holes drilled in the dust cover.

#### Circuit Description

#### Multi-vibrator (Fig. 9)

- 95. The multi-vibrator V2, V4 generates a positive pulse at the cathode and a negative pulse at the anode circuit of V4. The components are so proportioned that square pulses with sharp fronts are generated. The operation is essentially similar to that of a conventional multi-vibrator except that a resistance load R21, R22 is inserted in the common cathodes of V2 and V4. The resistor R15 and condenser C3 serves to decouple the anode circuit of V2.
- 96. Referring to the waveforms in Fig. 10, when V2 cuts off due to a negative impulse applied to its grid from the anode of V4, a positive impulse is generated at its anode and applied to the grid of V4, causing it to conduct. The current surge through V4 produces a sharp fronted positive pulse at its cathode and simultaneously a negative pulse at its anode. V4 is held in this conducting state until V2 conducts again, i.e., for a period determined by the time constant of C9 and the grid resistor of V2.
- 97. Four grid resistors R6, R7, R8, R9 for V2 are selected by bank "B" of range switch S1 to give pulse durations slightly greater than 1000, 500, 100, 50 u/seconds, respectively corresponding to ranges of 80, 40, 8, 4 nautical miles.

98. During the other phase of the MV cycle V4 is cut off and V2 conducts for a time determined by the grid circuit time constant of V4. Bank C of SW1 selects V4 grid resistors R10, R11, R12, R13 in the same sequence as bank B selects R6, R7, R8, R9. The combinations of the time constants of the circuit are such that the total repetition period of the MV on all ranges is approximately 2900 u/seconds corresponding to a P.R.F. of 350 + 50 cycles per second under all circumstances. Approximately 10% of the exponential charging curve of each condenser is used, thus a fairly linear sweep voltage is obtained.

- 99. Development of Push-Pull Deflection.—The output positive going waveform from V1 is fed to cathode coupled push pull amplifiers V3 (see Fig. 11) and V5, which in turn are direct coupled to the time base deflection plates of the cathode ray tube.
- 100. The grid of V3 is direct coupled to the anode of time-base grid V1 and assumes the same potential as the anode. The cathodes of V3 and V5 are returned to earth through common cathode resistor R29 and the voltage developed across this resistor is sufficient to cause V3 to operate at a point near cut-off. The grid of V5 is held at a positive potential with respect to earth developed at the junction of R35 and VR7. This voltage is sufficient to overcome the voltage developed across the cathode resistor R29, thus V5 normally draws current.
- 101. When the positive going waveform from V1 is impressed on the grid of V3 this valve conducts to a greater extent thus drawing increasing current through the common cathode resistor R29. This increases in current causes the voltage developed across R29 to rise and eventually overcome the positive potential on the grid of V5 causing this valve to reach cut-off point. Thus, as the potential at the anode of V3 is falling that at the anode of V5 is rising and a push-pull output is impressed across the deflection plates of the cathode ray tube.

Trace Calibration Control

- 102. The factors governing the actual velocity of the trace are:-
  - (a) the charging curve of the time-base condenser, C5, C7, C8 or C10.
  - (b) the amplification factor of the push-pull amplifier valves V3 and V5, and
  - (c) the sensitivity of the cathode ray tube. The adjustments provided for by VR1, VR2, VR3 or VR4 control the charging curves of the time base condensers but do not cover variations of (b) and (c).

To allow for variations in the amplification factor of valves used in positions V3 and V5 and variations in sensitivity of cathode ray tubes, a pre-set potentiometer VR5 is incorporated in the anode circuit of V3 and by controlling the amplification factor of V3 provides a compensating adjustment.

- 103. Elimination of "Flyback".—Coincident with the development of the time base pulse at the anode of V4, a positive going pulse is generated at its cathode. Portion of this pulse is taken from the junction of R21 and R22 and applied to the grid of cathode ray tube through a coupling condenser C18. This positive pulse decreases the negative potential on the grid of the cathode ray tube brightening up the trace for the duration of the pulse. As this pulse is of the same duration as the time base sweep time the cathode ray tube at the cessation of the pulse returns to its normal "blacked out" condition, until the beginning of the next sweep so that no flyback or stationary spots appear on the screen.
- 104. Video Deflection.—The positive video signal impulses from the switching motor are impressed upon the "X" plates of the cathode ray tube via the switching motor port output to port deflection plate through coupling condenser C22; starboard output to starboard deflection plate through C23. As the coupling condensers C22 and C23 will destroy the unidirectional form of the positive video signals, it is necessary to connect a diode D.C. restorer, i.e., one-half of V9, to each deflection plate in order to restore the signals to their former positive going waveform.
- 105. Vertical and Horizontal Shift Controls.—The potentiometer VR7 forms the vertical shift control and acts in the following manner:—The anodes of V3 and V5 are direct coupled to bottom and top deflection plates respectively. Normally V5 is conducting and V3 is operating with a very low value of anode current, thus the bottom deflection plate has a high positive potential with respect to the electron stream which, as a result, is drawn down to the bottom of the cathode ray tube screen.
- 106. The steady D.C. potential on the cathode of V1 is variable by means of VR7 and accordingly the minimum potential to which the condenser (C5, C7, C8 or C10) falls when discharged is variable with respect to earth. The potential across this condenser is direct coupled to the grid of V3 and the lower this potential falls the higher the positive potential at the anode of V3 and vice versa. Therefore any variation of the potential at the cathode of V1 is reflected at the cathode ray tube as a variation in the commencement of the trace.
- 107 The potentiometer VR6 forms the horizontal shift control and acts in the following manner:—The "X" plates of the cathode ray tube form the video deflection plates. The port deflection plate is held at a steady positive potential by the voltage drop across voltage divider R40 and R41. The positive potential on the starboard deflection plate can be varied between limits above and below the port X plate potential by the action of VR6. In normal operation when the moving contact of the VR6 is in the centre position the

accelerating anode and the port and starboard deflection plates assume equal potentials with respect to earth.

- 107. Cathode Ray Tube.—The cathode ray tube V8, type 1802 or 5BP1 operates with a high tension negative supply of approximately 1350 volts. This voltage is applied across the voltage divider network consisting of R42, VR8, R43, VR9. The moving arm of VR8 is connected to the focusing anode and operates as a focus control. VR9 operates as the brilliance control.
- 109. The "Y" plates during each time base sweep cycle assume high positive potential with respect to the accelerating anode the speed of the electrons would be further accelerating anode the speed of the electrons would be further accelerated by the "Y" plates, causing poor focusing qualities. To reduce the potential dieffrence between the deflection plates and the accelerating anode the latter is connected to a + 250 volt source at the junction of R33 and R34. A further effect is that this voltage is complementary to the -1350 volt supply and therefore the total potential between accelerating anode and earth is -1600 volts.
- 109. Pulse Amplifier.—Portion of the negative pulse developed at the anode of V4 is taken from the junction of R19 and R20 and fed through coupling condenser C12 to grid of V6 which operates as a voltage amplifier. A negative pulse impressed on the gri dof V6 will appear as a positive pulse of greater magnitude at its anode. A cathode follower V7 is used to match the anode impedance of V6 to the low impedance cable output.
- 110. Remote Control of Transmitter High Tension. Two spring loaded press-button switches SW3 and SW4 and relay Rel.1 form the remote control switch for the transmitter high tension. Normally SW4 is open and SW3 is closed. The high tension circuit is then completed through SW2 and SW4 is out of circuit. To switch off the transmitter SW3 is pressed, thus breaking the circuit through Rel.1 which releases SW2.
- 111. Power Supply.—The indicator power supply section consists of transformer T1, ½ wave rectifier valve V10, and associated filter circuit. The primary of transformer T1 is designed for operation off 80 v. A.C. 200° C.P.S., a tap being provided for operation off 115 v. A.C. T1 has a high tension secondary to give a filtered output of —1350 volts, a rectifier filament winding 2.5 v. 1.75 amps, a cathode ray tube filament winding 6.3 v. 0.6 amps and a 6.3 v. 2.5 winding for the indicator valve filaments. C20 and C21, are filter condensers in conjunction with filter resistor R44, forming the filter network for the cathode ray tube high tension. The high tension +320 volts for the remaining indicator valves is obtained from the transceiver power supply. All power supply input connections are via the 12 pin socket S4.
  - 112. Socket connections for all valves used in Rebecca IIB appear in Fig. 13.

#### CHAPTER 4

#### Aircraft Power Supplies

General — Motor Alternator Type MA6 — Control Panel Type RD-21

Introduction

- 114. The Rebecca transceiver and indicator uints are designed to operate from an alternating current power supply of 80 volts at a frequency of 2000 cycles per second.
- 115. To provide a power supply for Rebecca equipment when used in C.47 aircraft, a motor alternator type MA-6 is used. The motive power for the motor portion of the MA-6 is obtained from the aircraft D.C. supply.
- 116. To ensure that the correct voltage is maintained at the input terminals of the Rebecca units, under all load conditions, the output from the alternator is kept constant at 80 volts by a carbon pile regulator located in the control panel type RD.21. The front panel of this unit serves as a distribution panel for the power supplies to the various Rebecca units.

## Motor Alternator MA-6

- 117. The motor alternator type MA-6 consists of a D.C. motor which drives an alternator having a rated output of 250 watts at 80 volts and a frequency of 2000 cycles per second. The motor and alternator are constructed as an integral unit and mounted on a cast mounting base as shown in (lower) page 14.
- 118. The physical dimensions of the complete unit are: length, 11 ins.; diameter,  $5\frac{1}{2}$  ins.; weight, 25 lbs. The motor is designed to operate from the 28.5 volt D.C. aircraft supply with a rated input of 18 amps. The alternator rotor, motor armature and ventilating fan are all mounted on one shaft, the shaft bearings being located in the end plates of the housing assembly. The shaft speed on full load is approximately 5000 r.p.m, and the frequency of the alternator output at this speed is 2000 cycles per second. This supply frequency is normal radar practice as it enables the power transformer and filter chokes in the various units to be constructed with small sized cores and windings.

#### Control Panel Type RD-21

120. The function of the control panel is to regulate the output from the alternator, to provide a distribution panel for branching the power supply to the Rebecca units, and also to control the alternator-field energizing voltage.

- 121. The control panel comprises the following sections:
  - (a) Voltage regulator.
  - (b) Power factor correction condenser.
  - (c) R.F. filter circuit.
  - (d) Power distribution panel.
- 122. The voltage regulator type E as used in the control panel consists of:-
  - (i) a pile of carbon discs under pressure, the resistance of which varies inversely as the pressure varies; and
  - (ii) a solenoid assembly energized by a voltage obtained from the output of the alternator, and rectified by a selenium rectifier. The armature of the solenoid is so linked to the carbon pile that changes of the magnetic field of the solenoid caused by fluctuations in the alternator output are inversely reflected in the carbon pile as changes of pressure.
- 123. The regulator is adjusted so that under normal load conditions and alternator rotor speed the output from the alternator is 80 volts. Should this output voltage rise, either as a result of reduced load or increased rotor speed the rectified voltage in the solenoid will likewise rise. The increased field in the solenoid will further attract the armature and cause the pressure on the carbon pile to be reduced with the result that the resistance of the carbon pile is increased. The carbon pile is in series with the alternator field, and the increased voltage drop across the pile reduces the field excitation so that the alternator output falls to the required 80 volts. On the other hand, should increased load or reduced rotor speed cause the alternator output to fall, the pull exerted by the solenoid on the armature is relaxed allowing a spring to exert increased pressure on the carbon pile. This results in a decrease in the resistance of the carbon pile and consequently a lower voltage drop across it. As a result of this reduced voltage drop the field excitation voltage is increased and the alternator output rises to 80 volts.
- 124. To provide a means of introducing sufficient capacity into the power supply circuit as compensation for inefficient values of power factor two condensers can be connected in circuit either singly or in parallel, providing three values of capacity.
- 125. A filter circuit comprising four R.F. chokes and four bypass condensers, the whole being enclosed in a metal box, is included in the D.C. input circuit of the control panel. The input socket, on the front panel, and the leads from this socket to the filter unit are effectively shielded. This shielding and filter circuit is necessary to preventing the following forms of interference being superimposed on the aircraft D.C. supply; (a) 2000 cycles per second ripple from the alternator; (b) 350 cycles per second pulse note or any R.F. component.
- 126. The output from the alternator is required to be supplied to several units at the one time and to facilitate this, three 4-pin sockets are mounted on the front panel. Pins Nos. 1 and 2 are the 80 volt A.C. output connection and pins Nos. 3 and 4 are the D.C. output connections. A 5 amp fuse is connected in one 80 volt lead to each socket. These fuses are fitted on a fuse panel which holds a total of six fuses, three of which are spares. In addition to the three power supply sockets the following sockets are fitted to the control panel; (a) a 2-pin socket for the D.C. input to the control panel; (b) a 6-pin socket for connection to the motor-alternator MA-6; and (c) a 2-pin amphenol socket which permits of remote control of the 28.5 volt D.C. input to the control panel by a switch box. The latter is located conveniently near the operator.

## CHAPTER 5

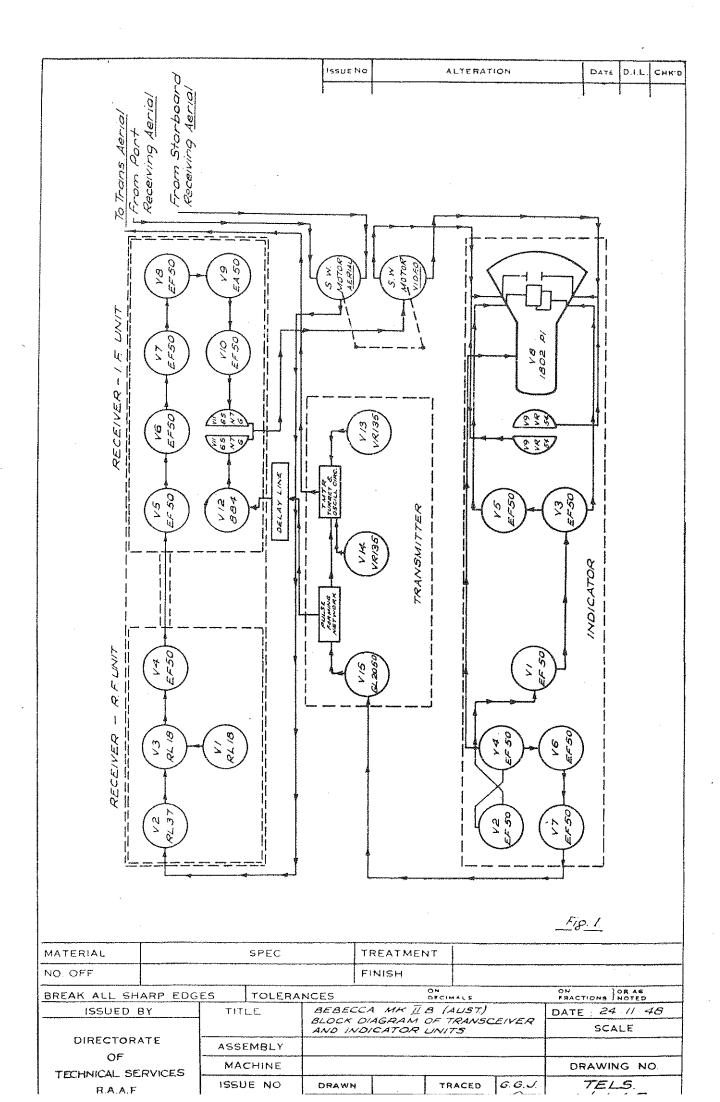
## Spares for Rebecca

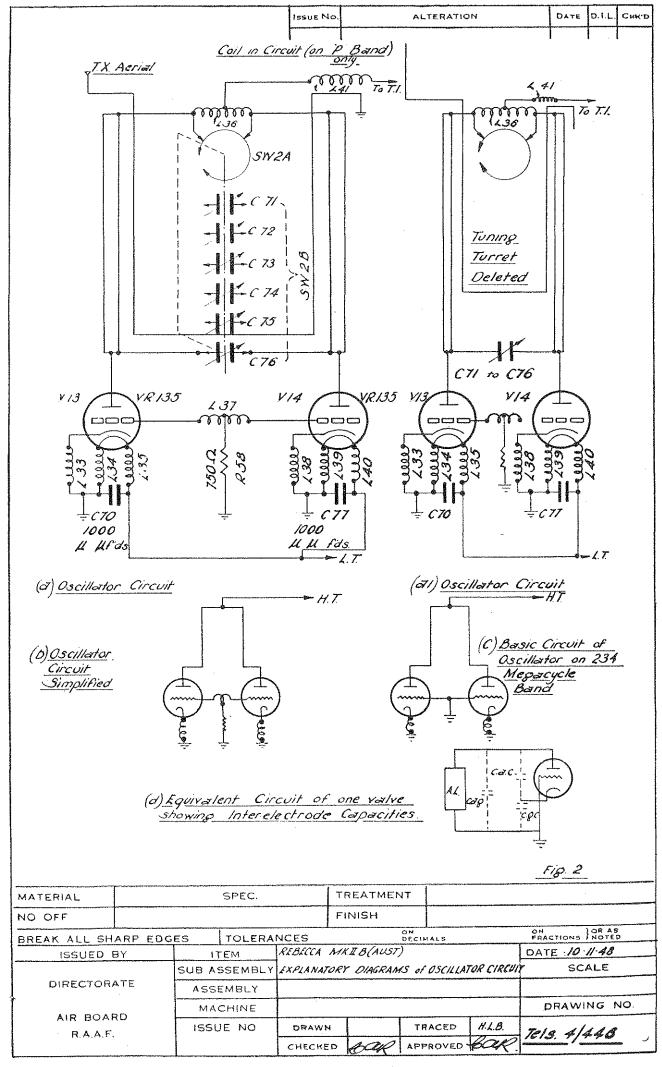
## DETAILS OF COMPONENTS

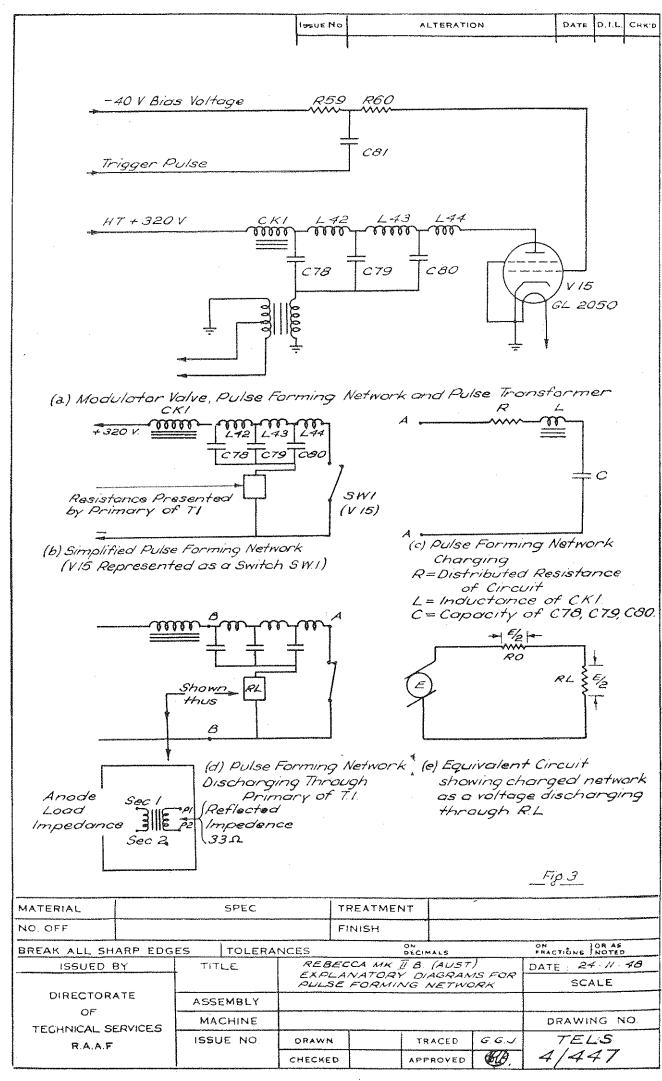
Item No.	Ident No.	Nomenclature	Detail	HMV Part No.	Quantity per Uni
1 2 3 4 5 6	Y10AB/500149 Y10AB/500217 Y10AB/500218 Y10AB/500219 Y10AB/500254 Y10AB/500255	Clip, grid type D4420 Trays, mounting type RD21 Trays, mounting type B2141 Trays, mounting type B2143 Turret, support type C3193 Turret, support type C3194	For EA50 Valve For Control panel For Indicator For Transceiver Cast aluminium receiver Cast aluminium transmitter	D4420 B2142 B2143 C3193 C3194	4
7 8	Y10AB/500256 Y10AB/500257	Knob, type D5053/A  Guide, tuning tool type D5370	Modified MIK6 Including D5407 Captive Screw (Cream Bakelite) Tuning tool guide	D5053/A - D5370	2 3
9 10 11 12	Y10AB/500258 Y10AB/500259 Y10AB/500260 Y10AB/500261	Panel, (contact mounting type D5335) Knob, type D5417 Coupling, moulded type D4187 Knob, type D5647/A	Modified MIK 9 Moulded Bakelite R3d dot PK	D5335 D5417 D4187 D5647/A	2 3 1 2 4 1
13 14 15 16 17 18	Y10AB/500262 Y10AB/500263 Y10AB/500264 Y10AB/500265 Y10AB/500266 Y10AB/500267 Y10AB/500268	Knob, type D5647/B Knob, type D5647/C Grommet, type D5424 Grommet, type D5425 Grommet, type D1748 Spring, type D4201 Spring, type D5365	screw Moulded Bakelite blue dot Moulded Bakelite yellow dot	D5647/B D5647/C D5424 D5425 D1748 D4201 D5365	1 1 2 4 18
20 21 22 23	Y10AB/500269 Y10AB/500270 Y10AB/500271 Y10AB/500272	Panel, front type C3191 Panel, front type C3190 Screen, perspex type O3195 Escutcheon, type D4170/B	Transceiver Indicator For indicator A1047 For covering V & H shift con-	C3191 C3190 C3195 D4170/B	
24 25 26	Y10AB/500273 Y10AB/500274 Y10AB/500275	Clip, retaining type D5427 Nut, knurled type D4379 Guide, assembly type D3544/X	trols on indicator For A50 valve For A50 valve retaining clip Consists of guide tube washers guide post captive screw, screw 2BA2 CHSP washer 36 in.	D5427 D4379 D5344/X	8
27 28 29 30	Y10AB/500276 Y10AB/500277 Y10AB/500278 Y10AB/500279	Cover, dust indicator type B2144 Cover, dust trans-receiver type B2145 Shield, for G.R.O. type C3164 Mounting, anti-vibration type 118/60	Ormiston	B2144 B2145 C3184	8
31 32 33 34 35 36 37 38	Y10AB/500280 Y10AB/500281 Y10AB/500282 Y10AB/500283 Y10AB/500284 Y10AB/500286 Y10AB/500286 Y10AB/500287	Retainer, valve type D4320/A Retainer, valve type D/4320/B Retainer, valve type D5315 Retainer, valve type D5373 Spanners, type D5374 Hood, visor retaining type D5543 Base, Mounting type D5334 Panel, (grid coil) type D5333		D4320/A D4320/B D5315 D5373 D5374 D5543 D5334 D5333	1 14 2 2 1 1
39 40 41 42 43 44 45	Y10AB/500288 Y10AB/500289 Y10AB/500290 Y10AB/500291 Y10AB/500292 Y10AB/500293 Y10C/65758	Washer, belt type D5554 Tool, tuning type D5376 Clip, grid type D0959 Ring, packing type D4199 Ring, retaining rubber type D4200 Clamp, support CR valve type D5318 Resistor, 150,000 ohms 1 watt	Ducon ± 10%	D5554 D5376 D0959 D4199 D4200 D5318 D0244/K3X	1 2 1 4 1 1
46 47 48 49 50	Y10C/65161 Y10C/65730 Y10C/67201 Y10C/66014 Y10C/67202 Y10C/65718	Resistor, 500 ohms & watt carbon Resistor, 10,000 ohms & watt carbon Resistor, 15,000 ohms & watt carbon Resistor, 35,000 ohms & watt carbon Resistor, 750 ohms & watt carbon Resistor, 100 ohms & watt carbon	Ducon IRC Ducon Ducon Ducon Ducon	BIX F2X D2X G2X CIX T1X	5 1 1 3 5
52 53 54 55 56 57 58	Y10C/65944 Y10C/65670 Y10C/67203 Y10C/65183 Y10C/67204 Y10C/66379 Y10C/65163	Resistor, 200 ohms ½ watt carbon Resistor, 1,000 ohms ½ watt carbon Resistor, 1,200 ohms ½ watt carbon Resistor, 2,000 ohms ½ watt carbon Resistor, 2,200 ohms ½ watt carbon Resistor, 10,000 ohms ½ watt carbon Resistor, 20,000 ohms ½ watt carbon Resistor, 20,000 ohms ½ watt carbon	Ducon Ducon IRC ± 5%  Ducon ± 5% IRC	XHIX DIX BU2V AJIX DD2V F3X VIX	9             
59 60 61 62 63 64	Y10C/65160 Y10C/66273 Y10C/67205 Y10C/67206 Y10C/66942 Y10C/6575	Resistor, 50,000 ohms ‡ watt carbon Resistor, 5,000 ohms I watt carbon Resistor, 8,000 ohms ½ watt carbon Resistor, 10,000 ohms ½ watt carbon Resistor, 15,000 ohms ½ watt carbon Resistor, 20,000 ohms I watt carbon	IRC ± 5%, IRC ± 5%, IRC ± 5%	HIX X3X BJ2V F2V AD2V V3X	1 2 4 2 2 4 3 1
65 66 67 68 69 70	Y10C/66339 Y10C/65169 Y10C/66269 Y10C/65165 Y10C/65750 Y10C/66214	Resistor, 30,000 ohms 2 watt carbon Resistor, 50,000 ohms ½ watt carbon Resistor, 250,000 ohms ½ watt carbon Resistor, 500,000 ohms ¼ watt carbon Resistor, 500 ohms I watt carbon Resistor, 600 ohms I watt carbon	IRC — T or mills Ducon IRC  Ducon Ducon	W4X L1X N2X D1X B3X BA3X	2
71 72 73 74 75	Y10C/65159 Y10C/65662 Y10C/67207 Y10C/65576 Y10C/67208 Y10C/65577	Resistor, 2,000 ohms I watt carbon Resistor, 3,000 ohms, I watt carbon Resistor, 10,000 ohms I watt carbon Resistor, 25,000 ohms I watt carbon Resistor, 25,000 ohms 2 watt carbon Resistor, 40,000 ohms I watt carbon	IRC Ducon ±2%  IRC B.T. or mills ± 2%	AJ3X AF3X F3T AE3X AE4T S3X	1 ! ! 3 4
76 77 78 79 80	Y10C/67209 Y10C/66381 Y10C/66826 Y10C/67210	Resistor. 40,000 ohms I watt carbon Resistor, 50,000 ohms I watt carbon Resistor, 60,000 ohms I watt carbon Resistor, 60,000 ohms 2 watt carbon	Ducon ± 2%  IRC B.T. or mills	S3T H3X AT3X AT4X	1 1 2
79	Y10C/66826	Resistor, 50,000 ohms I watt carbon Resistor, 60,000 ohms I watt carbon		H3X AT3X	

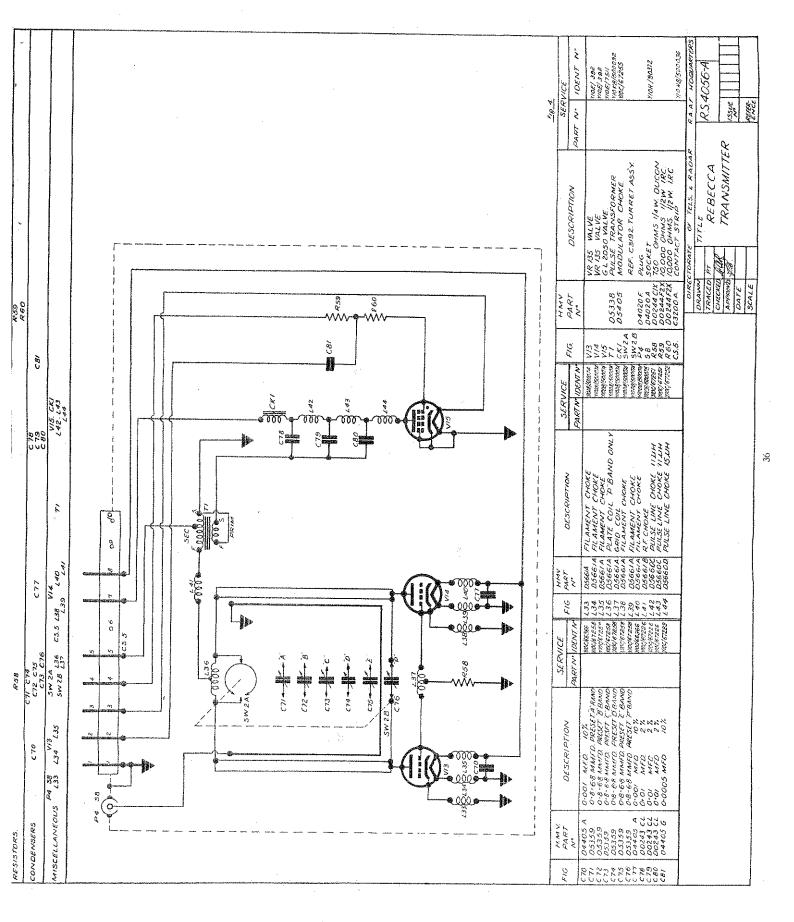
Strice		Item No.	Ident No.	Nomenclature	Detail	HMV Part No.	Quantity per Unit
91 VIOC.05248 Sections, 1 strongenis 1 water cachenomy of the complete of the	e e	84 85 86 87 88 89	Y10C/65299 Y10C/66472 Y10C/67212 Y10C/66310 Y10C/65580 Y10C/67213	Resistor, 250,000 ohms 1 watt carbon Resistor, 250,000 ohms 2 watt carbon Resistor, 400,000 ohms 1 watt carbon Resistor, 500,000 ohms ½ watt carbon Resistor, 500,000 ohms I watt carbon Resistor, 500,000 ohms I watt carbon	IRC B.T. or mills Ducon ± 2% I.R.C. IRC ± 10	N3X N4X AU3T O2X O3X O3T D0244/	5 2
110   Y10C/67227   111   Y10C/67237   112   Y10C/6724   113   Y10C/6724   114   Y10C/6724   115   Y10C/6724   115   Y10C/6724   116   Y10C/6724   116   Y10C/6725   116   Y10C/6725   116   Y10C/6725   116   Y10C/6726   116   Y1		92 93 94 95 96 97 98 99 100 101 102 103 104 105 106 107	Y10C/67215 Y10C/67216 Y10C/67218 Y10C/67219 Y10C/67220 Y10C/65222 Y10C-66366 Y10C/66363 Y10C/66363 Y10C/67221 Y10C/67222 Y10C/67223 Y10C/67223 Y10C/67225 Y10C/67225 Y10C/67225	Resistor, 1·1 megohm I watt carbon Resistor, 1·25 megohm I watt carbon Resistor, 2 megohm I watt carbon Resistor, 2 megohm I watt carbon Condensor, 4mmfd tubular ceramic ± ·5 mmfd Condensor, 10 mmfd tubular ceramic ± I mmfd Condenser ·25 mmfd tubular ceramic ± I mmfd Condenser, 1.000 mmfd mica uncased ± 10% Condenser, 200 mmfd mica uncased ± 10% Condenser, 50 mmfd mica uncased ± 10% Condenser, 100 mmfd Condenser, 100 mmfd Condenser, 100 mmfd Condenser, 200 mfd mica uncased ± 10% Condenser, 500 mfd mica uncased ± 10% Condenser, 500 mfd mica uncased ± 10% Condenser, 1,000 mfd mica uncased ± 1% Condenser, 1,000 mfd mica uncased ± 10% Condenser, 1,000 mfd mica uncased ± 10% Condenser, 000 mfd mica moulded ± 2% Condenser, 000 mfd mica moulded ± 10% wire	Ducon style B N.P.O. Ducon style B N.P.O. Ducon style B N.P.O. Ducon style B N. 750 Simplex A/S Simplex P/T Simplex P/T	P3X DB3T AX3T AA3X D5411/B D5411/C D5411/D D5411/E D4405/A D4405/H D4405/F D4405/S D4405/S D4405/G D4405/R D0243/CO D0243/H	98 3 1 2 2 3
114   Y10C/66722   Condenser, 01 mid mice moulded ± 11%   C,000y   Condenser, 02 mid name moulded ± 11%   C,000y   Condenser, 03 mid paper metal cased 600 volt   Condenser, 03 mid paper metal cased 600 volt   C,000y		111 112	Y10C/67227 Y10C/67228	Condenser, ·0025 mfd mica moulded ± 1% Condenser, ·005 mfd wire moulded ± 1% wire ends Condenser, ·01 mfd mica moulded ± 2% wire ends	Simplex S/E Simplex S/E	D0243/CT D0243/CL	1 1 3
131   Y10C/67258   Condenser, tuner assembly transmitter type D559   D5599   6     132   Y10C/67240   Detentiometer 250,000 ohms Allen-Bradley type   (Modified)   Detentiometer, 100,000 ohms Allen-Bradley type   (Modified)   D5666   I     134   Y10C/67241   Detentiometer, 100,000 ohms Allen-Bradley type   (Modified)   D56667   I     135   Y10C/67242   Detentiometer, 100,000 ohms Allen-Bradley type   (Modified)   D55666B   4     136   Y10C/67243   Detentiometer, 100,000 ohms Allen-Bradley type   (Modified)   D5406   D55666B   4     137   Y10C/67243   Detentiometer, 100,000 ohms airzone w-w (Modified)   D4194   1     138   Y10C/67249   Detentiometer, 2,000 ohms airzone w-w (Modified)   D5406   D4194   1     140   Y10C/67249   Choke, Rf type D5660B 447UH   L5660B   D5591   L5660B   D5591   L5660B   D5591   L5660B   D5666B   D5591   L5660B   D5666B		115 116 117 118 119 120 121 122 123 124 125 126 127 128 129	Y10C/67229 Y10C/66726 Y10C/67230 Y10C/67231 Y10C/67232 Y10C/67233 Y10C/67234 Y10C/66516 Y10C/66516 Y10C/65210 Y10C/65236 Y10C/65236 Y10C/657236 Y10C/65738 Y10C/65738	ends Condenser, '01 mfd mica moulded ± 10% (2,000v) Condenser, '025 mfd mica moulded ± 1% Condenser, 3x mfd paper metal cased 600 volt Condenser, 2x ·5 mfd paper metal cased 600 volt Condenser, 2x ·01 mfd paper metal cased 2,000 volt Condenser, '05 mfd paper metal cased 600 volt Condenser, '05 mfd paper metal cased 600 volt Condenser, '05 mfd paper metal cased 400 volt Condenser, '05 mfd paper metal cased 400 volt Condenser, '1 mfd paper metal cased 400 volt Condenser, '25 mfd paper metal cased 400 volt Condenser, '5 mfd paper tubular 400 volt Condenser, '05 mfd paper tubular 400 volt Condenser, '05 mfd paper tubular 400 volt Condenser, '05 mfd paper tubular 400 volt Condenser, '8 mfd electrolytic 600 volt type EG Condenser, ('25 mfd 200v) + (1·8 mfd 130v paper	Simplex M Simplex M Ducon Part No. P.S.T. 30 Ducon Part No. P.S.T. 31 Ducon Part No. P.S.T. 26 Ducon Part No. P.S.T. 82 Ducon Part No. P.S.T. 82 Ducon Part No. P.S.T. 82 Ducon Part No. P.S.T. 83 Ducon Part No. P.S.T. 83 Ducon Part No. P.S.T. 83 Ducon Part No. P.S.T. 86 Ducon Part No. P.S.T. 31	D0243/CK D0243/CN C3005/SS 3C005/SH C3005/SQ C3005/BJ C3005/BJ C3005/SK C3005/SJ C3005/SJ C3005/SO C3005/SO C3005/BE C3005/BE C3005/BE C0013/E C0013/G C0014/BT	4
134		132	Y10C/67239	Condenser, tuner assembly transmitter type D5359 Potentiometer 250,000 ohms Allen-Bradley type J (Modified)	one can)	D5665	6   
Modified  ( + 29% - 0)		134	Y10C/67241	Potentiometer, 50,000 ohms Allen-Bradley type J			1 4
139   Y10C/67259   Choke, RF type D5660A 208UH   Y10C/67251   Y10C/67251   Y10C/67251   Y10C/67252   Y10C/67252   Y10C/67252   Y10C/67253   Y10C/67254   Y10C/67255   Y10C/67255   Y10C/67255   Y10C/67256   Y10C/67256   Y10C/67256   Y10C/67256   Y10C/67256   Y10C/67256   Y10DB/500074   Y10C/67256   Y10DB/500078   Y10DB/500078   Y10DB/500078   Y10DB/500078   Y10DB/500078   Y10DB/500078   Y10DB/500080   Y10DB/		136 137	Y10C/67243 Y10C/67244	(Modified) (+ 20% -0) Potentiometer, 5,000 ohms airzone w—w (Modified) Potentiometer, 2,000 ohms airzone w—w (Modified) Potentiometer, 15,000 ohms marquis w—w	•	D5406 D4194	1
153		140 141 142 143 144 145 146 147 148 149 150	Y10C/67250 Y10C/67251 Y10C/67252 Y10C/67253 Y10C/67254 Y10C/67255 Y10C/67256 Y10C/67257 Y10DB/500074 Y10DB/500075 Y10DB/500076 Y10DB/500077	Choke, RF type D5660A 208UH Choke, RF type D5660B 417UH Choke RF type B5660C 211UH Choke RF type D5660D 15UH Choke RF type D5660E 310UH Choke, RF type D5660F 155UH Choke, transmitter pulse type D5405 Choke, power supply 2 Henry type D5456 Choke, indicator 3 Henry type D5372 Coil U.H.F. type D5661/A Coil, U.H.F. type D5661/C Coil, U.H.F. type D5661/C Coil, U.H.F. type D5661/D	Circuit ref. No. CK1  Set of 12 coils D5663 to	L5660B D5660C D5660D D5660E D5660F D5405 D5456 D5372 D566A1 D5661B D5661C D5661D D5663A to	1 1 1 11 18 18 1 5
163 Y10F/80214 Switch, toggle alpha S.P.D.T. Tropic-proofed D1109 I		154 155 156 157 158 159 160 161	Y10DB/500080 Y10DB/500081 Y10DB/500082 Y10DB/500083 Y10DB/500084 Y10DB/500085 Y10DB/500086 Y10DB/500087	Coil, transmitter plate type D5664B Coil, aerial (RF unit) type D5664C Transmitter, unit Receiver, unit type B2148 I.F., channel unit type B2149 Main, chassis unit type A1046 Turret assembly, (transmitter type C3192) Turret assembly, receiver type C3296	Complete Complete Complete Complete with front panel Complete Complete Set of 12 coils D5662A to	D5664A D5664B D5664C B2147 B2148 B2149 A1046 C3192 C3296 D5662A to	
164 Y 10FB/155 Switching, motor type 33A 165 Y 10FB/500063 Switch, 3 pole 4 pos. shorting ceramic 2 bank type Slotted shaft 1 % in. long		164	Y10FB/155	Switching, motor type 35A	Tropic-proofed	Di 109	
166 Y10FB/500064 Switch, push button type D5307A Normally open Normally closed D5307B   D5307		166	Y10FB/500064	D5325 Switch, push button type D5307A	Normally open		

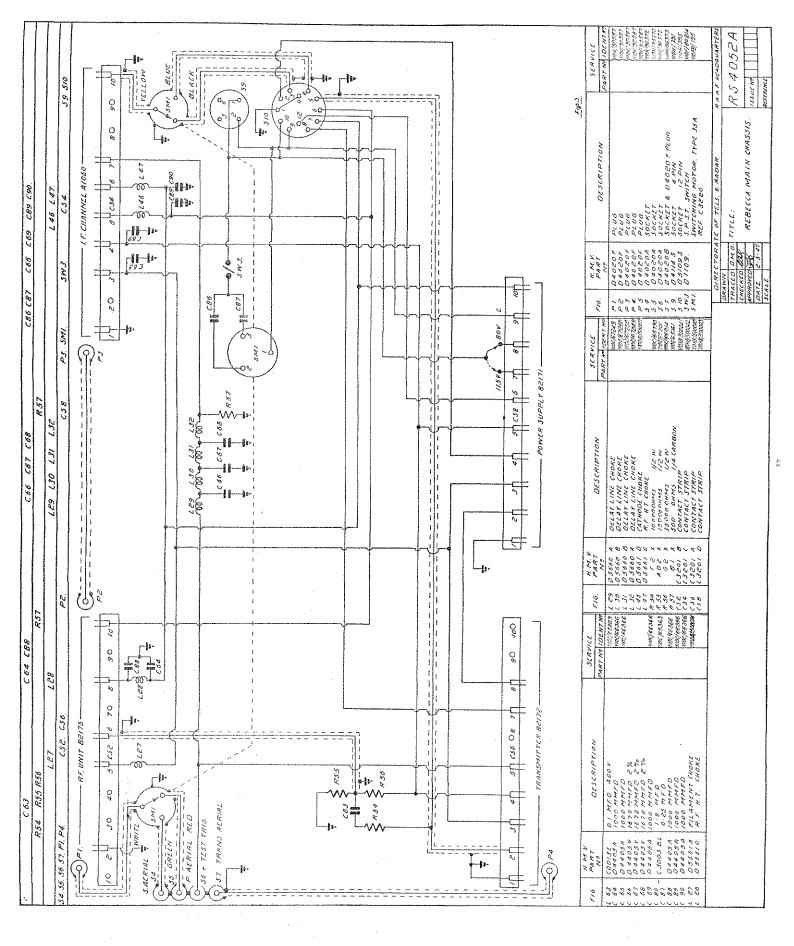
Item No.	Ident No.	Nomenclature	Detail	HMV Part No.	Quantity per Unit
168	Y10FB/500066	Relay, type D5423	S.T.C.	D5423	l
169	Y10H/379	Socket valve, 9 in. wafer type CXS265	E.F. 50/CXS265		14
170	Y10H/391	Plug, type W198	4 pin chassis mounting	D4114/S	į į
171	Y10H/395	Plug, type W202	12 pin chassis mounting	D5109/S	2
172	Y10H/90186	Socket valve, 4 pin steatite type RSS4	Type RSS4	1	
173 174	Y10H/90218 Y10H/90359	Socket valve, octal steatite type SS8   Socket valve, EA50	Type SS8		9 3
175	Y10H/90371	Socket, amphenol type P.C. 2F.		D4258	
176	Y10H/90372	Socket, type D4020A	Coaxial pye type	D4020/A	10
177	Y10H/90373	Socket, type D4020B	Coaxial pye type	D4020/B	i
178	Y10H/90436	Socket, valve 11 pin magnal			1
179	Y10H/90572	Socket, type W162A		D5110/P	2
180	Y10H/90587	Socket, type D4020/F	Coaxial pye type	D4020/F	13
181 182 :	Y10H/90588 Y10HB/500025	Socket, type H158	Miniature BC	D0042/A	1 4
183	Y10HB/500025	Strips, terminal 4 tag type D0042/A Strips, terminal 4 tag and bush type D0042/D		D6542/D	1
184	Y10HB/500027	Strips, terminal 8 tag type D0045/A		D0045/A	;
185	Y10HB/500028	Strips, terminal 1 tag type D0581	•	D0581	l ii
186	Y10HB/500029	Strips, terminal 2 tag and bush type D1248/B		S1248/B	2 2
187	Y10HB/500030	Strips, terminal 6 tag type D1283	ANOMANA ANA ANA ANA ANA ANA ANA ANA ANA ANA	D1283	2
188	Y10HB/500031	Strips, terminal 3 lug type D5428		D5428	
189 190	Y10HB/500032	Strips, terminal 11 tag standard type D4183/11		D4183/11	2
191	Y10HB/500033 Y10HB/500034	Strips, terminal 28 tag standard type D/4183/28 Strips, terminal 2x 3 lug with bracket type D5541		D4183/28   D5541	3
192	Y10HB/500035	Strips, terminal I.F. channel		D5413	ĺí
193	Y10HB/500036	Strips, contact male type C3200/A	mayor mark	C3200/A	i
194	Y10HB/500037	Strips, contact male type C3200/B		C3200/B	1
195	Y10HB/500038	Strips, contact male type C3200/C		C3200/C	
196	Y10HB/500039	Strips, contact male type C3200/D		C3200/D	}
197	Y10HB/500040	Strips, contact female type C3201/A	1	C3201/A	
198 199	Y10HB/500041 Y10HB/500042	Strips, contact female type C3201/B Strips, contact female type C3201/C	· -	C3201/B C3201/C	[
200	Y10HB/500043	Strips, contact female type C3201/D		C3201/D	li
201	Y10HB/500086	Transformer, I.F. type D5535/A	No. 2	D5535/A	i
202	Y10HB/500087	Transformer, I.F. type D5535/B	No. 3	D5535/B	I
203	Y10HB/500088	Transformer, I.F. type D5535/C	No. 4	D5535/C	1
204	Y10HB/500089	Transformer, I.F. type D5535/D	No. 5	D5535/D	
205	Y10HB/500090	Transformer, I.F. type D5535/E	No. 6	D5535/E	
206 207	Y10HB/500091 H28/26201	Transformer, I.F. type D5535/F Grommet, type D5	No. 7   ∰" × 76" Dunlop	D5535/F	9
208	H28/26203	Grommet, type 118	16" × 18" Dunlop   16" × 11" Dunlop		5
209	H28/26204	Grommet, type 133	15" × 1" Dunion		ĺ
210	H29/26205	Grommet, type 154	$7\pi'' \times 4''$ Dyunlop		j
211	H28/26206	Grommet, type 151	⅓" × ⅔" Dunlop		
212	H28/26207	Grommet, type 148	" × ¾" Dunlop	]	]
213	H28/26208	Grommet, type 1	76" × 72" Dunlop		2 2
214   215	G5A/25084 G105C/2274	Lamp, 28 volt ·17 amp, 651 base Clip, fuse type D4012	Mazda 313	4012	2
216	Y110M/2611	Clip, grid type 550/7/1		4012	ĺ
217	Y110H/1908	Plug, type C2K		4259	
218	Y10E/75099	Valves, type VR150/30	Pretested for this equipment	,	<u> </u>
219	Y10E/75094	Valves, type 5V4G			1
220	Y10E/92	Valves, type EF50			13
221	Y10E/599	Valves, type RL18			2
222	Y10E/75269	Valves, type CV66			1 2
223 224	Y10E/392 Y10E/7511	Valves, type VR135 Valves, type GL.2050			4
225	Y19E/11400	Valves, type CR2500 Valves, type VR54			1
226	Y10E/75095	Valves, type 879			İ
227	Y10E/75182	Valves, type 65N7G			1
228	Y10E/75119	· Valves, type 884			1
229	Y10E/105	Valves, type EA50	an at l		
230	Y10E/75114	Valves, type 1802/5BP1	C.R. Tube		

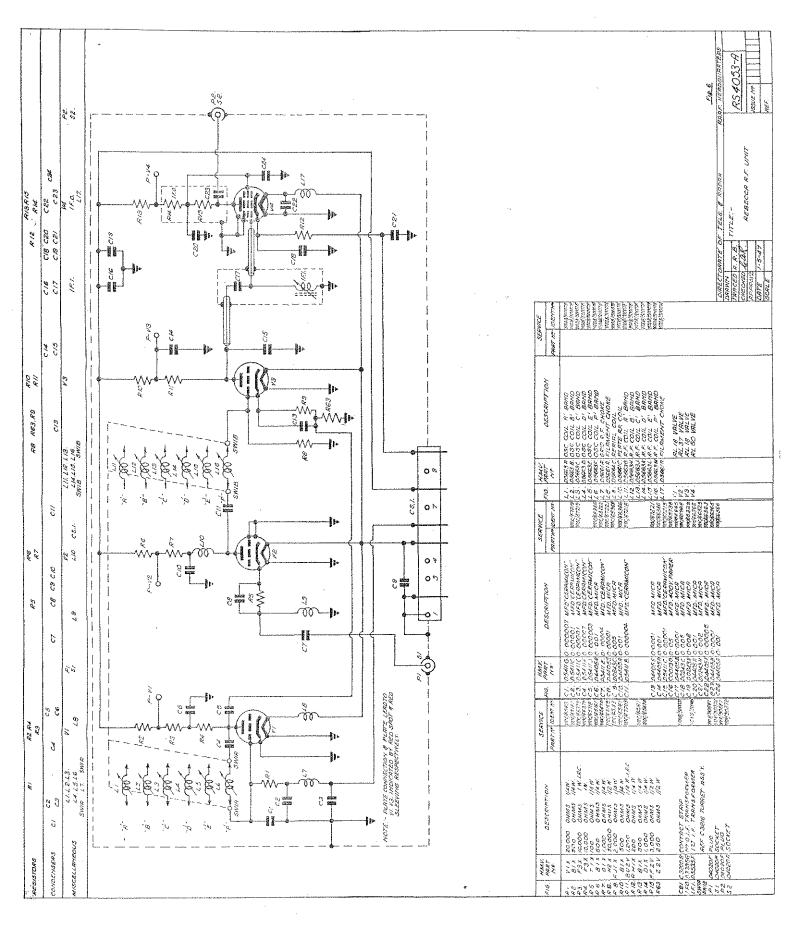


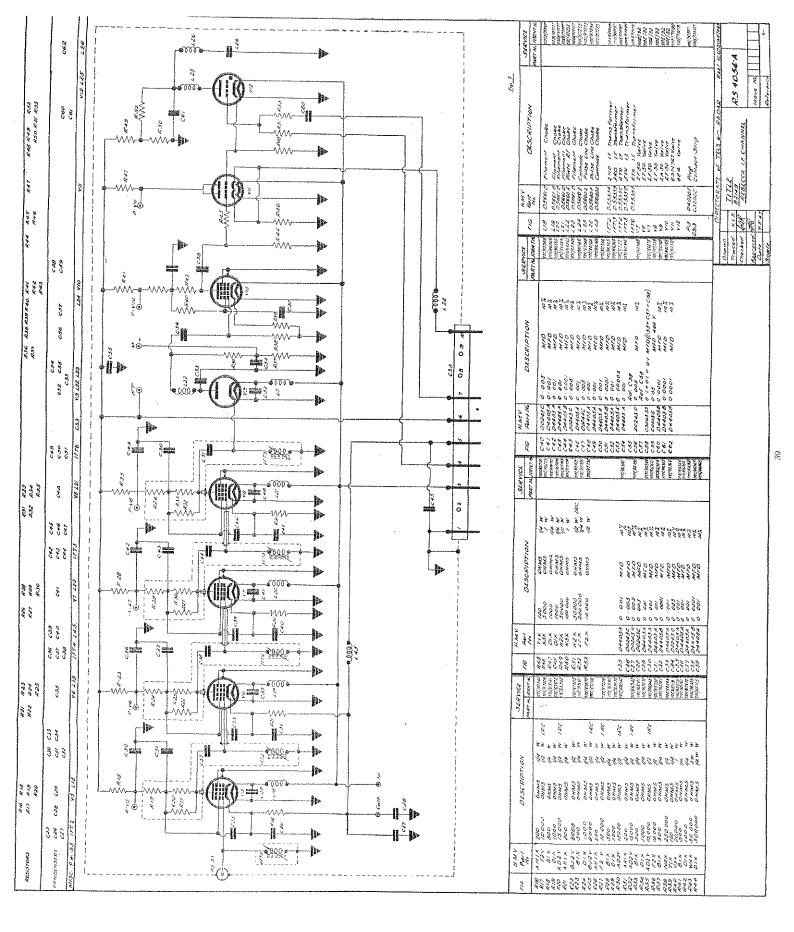


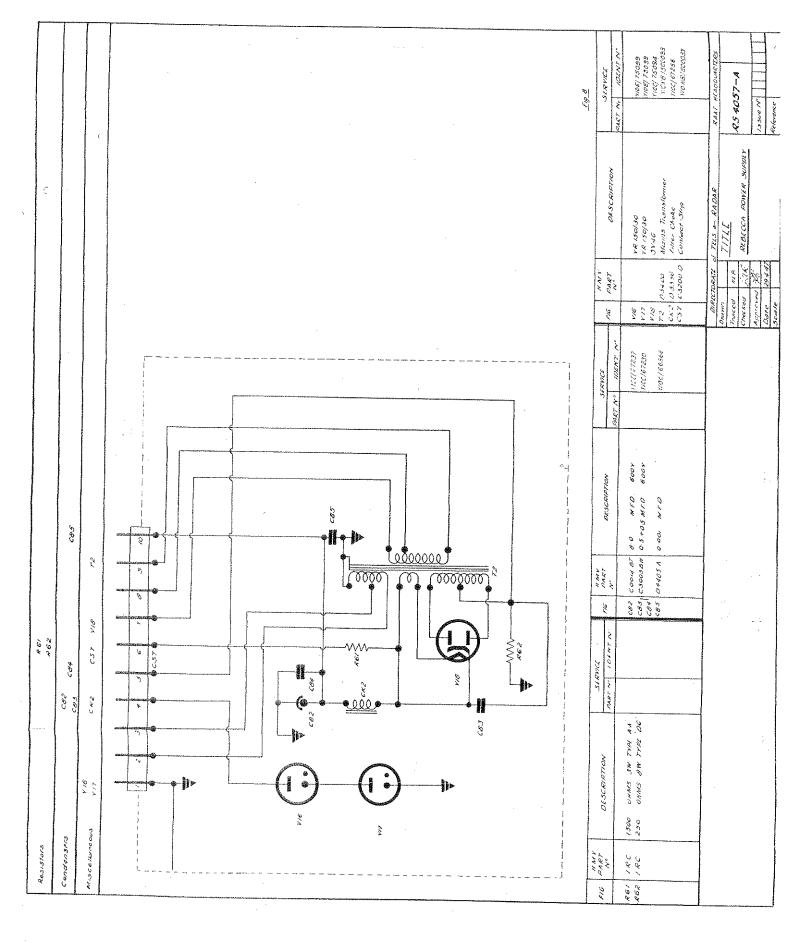


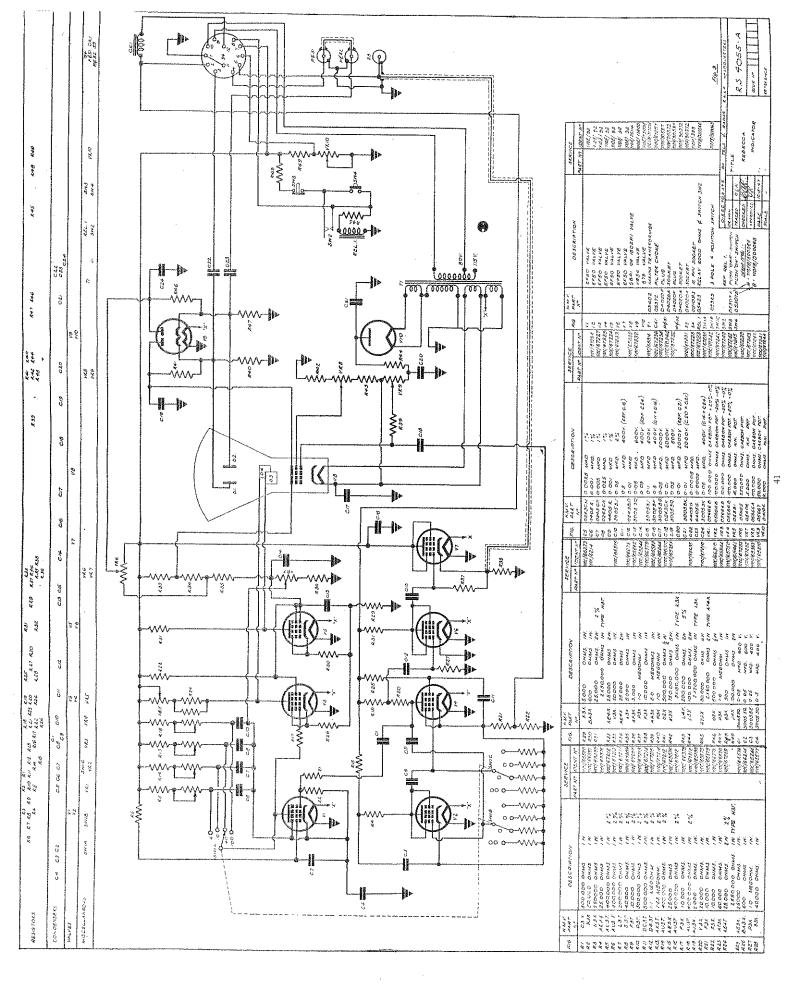


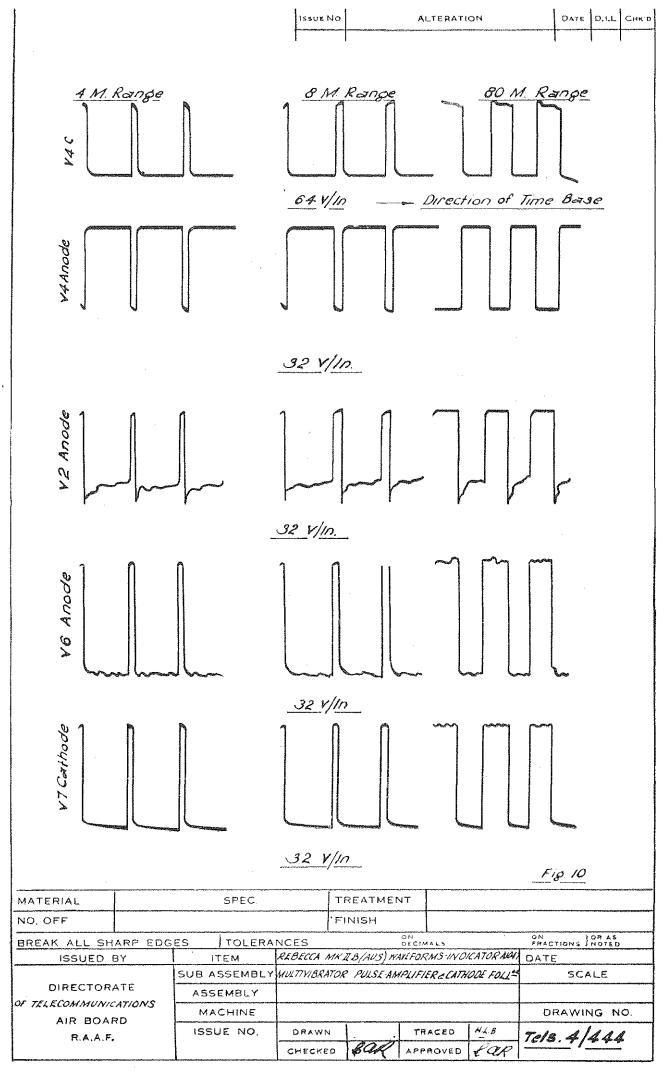




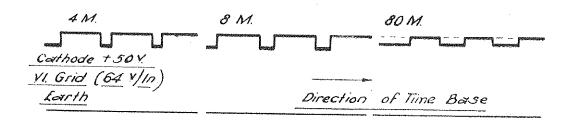








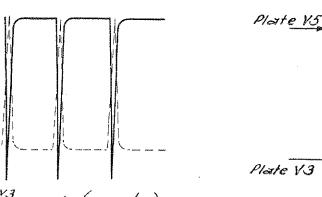


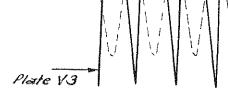


Cathode +50 V VI Anode (64 V/In)

Earth

## -H.T. Supply +300 Y.

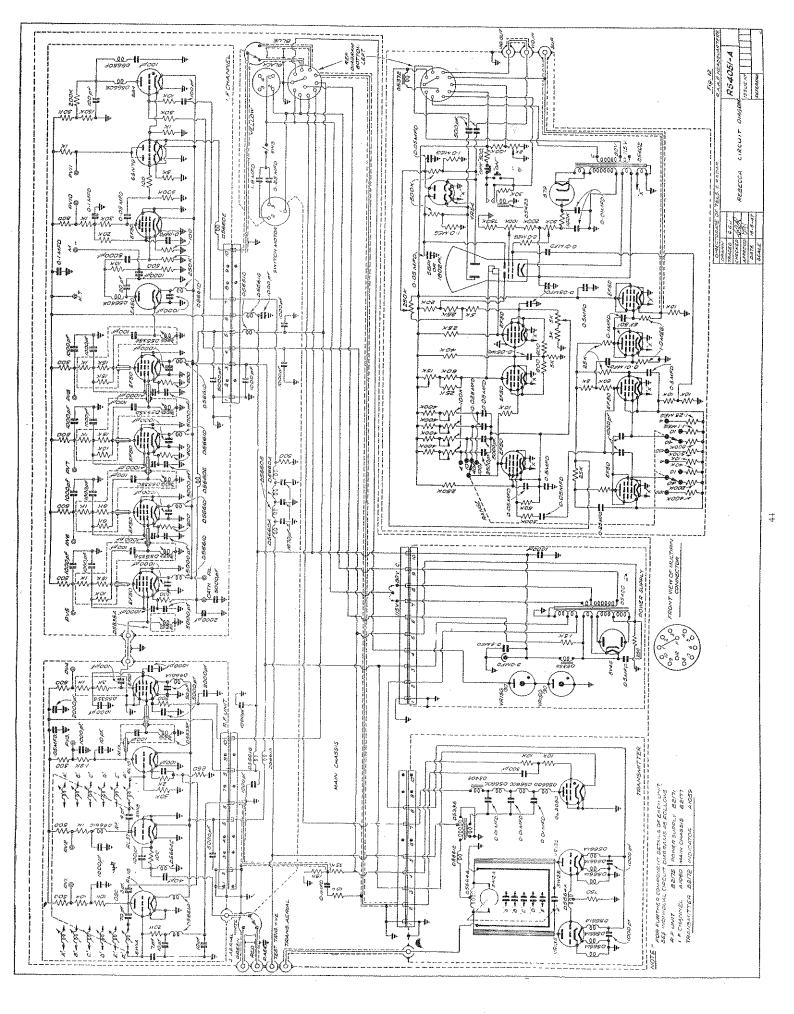




v3 Anode (100V/In)

Earth OY

						FIG 11
MATERIAL	SPEC.		TREATME	NT		
NO. OFF			FINISH		<del></del>	
BREAK ALL SHARP ED	GES TOLERA	NCES		ON / DECIMALS		ON CR AS
ISSUED BY	ITEM	REBECCA MA	(IB (AUST) W	AVEFORMS-IN	DICATOR	DATE : 4:11:48
0.0000000000000000000000000000000000000	SUB ASSEMBLY	A1047. TIM	TE BASE YAL	KK A PUSH PULL	AMPLIFIER	SCALE
OF TELECOMMUNICATIONS	ASSEMBLY				VI-17-17-11-11-11-11-11-11-11-11-11-11-11-	
AIR BOARD	MACHINE					DRAWING NO.
R.A.A.F.	ISSUE NO.	DRAWN		TRACED	MLB.	TELS.4/448
	<u> </u>	CHECKED	BOR	APPROVED	GOR	TARCE TO THE THE STATE OF THE S





-EF50/VR91-



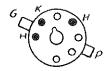
-<u>RL37/CV66-</u>



-6SN7GT-



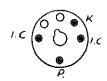
-884-



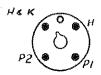
<u>-VR 135 -</u>



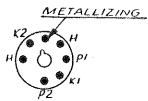
-GL 2050-



-VR150/30-(I.C. INTERNAL CONNECTION)



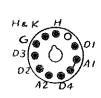
-5V4G-



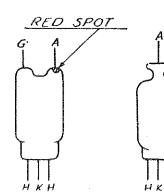
<u>-VR54</u>-



-879



-1802 <u>|58 P1</u>.-



-RL18- -EA50/VR92-

Fig. 13

DIRECTORATE OF TELS. & RADAR RAAF HEADQUARTERS DRAWN TITLE: RS 4050 A TRACED P.T. SOCKET CONNECTIONS CHECKED HOK REBECCA MK 2B APPROVED ISSUE Nº DATE 18.4.47 REFERENCE SCALE